Multi-Centered Invariants, Plethysm and Grassmannians

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Abstract

Motivated by multi-centered black hole solutions of Maxwell-Einstein theories of (super)gravity in $D = 4$ space-time dimensions, we develop some general methods, that can be used to determine all homogeneous invariant polynomials on the irreducible $(SL_h(p,\mathbb{R}) \otimes G_4)$-representation $(\mathbf{p}, R)$, where p denotes the number of centers, and $SL_h(p,\mathbb{R})$ is the *"horizontal"* symmetry of the system, acting upon the indices labelling the centers. The black hole electric and magnetic charges sit in the symplectic representation R of the generalized electric-magnetic (U-)duality group G_4.

We start with an algebraic approach based on *classical invariant theory*, using Schur polynomials and the Cauchy formula. Then, we perform a geometric analysis, involving Grassmannians, Plücker coordinates, and exploiting Bott's Theorem.

We focus on *non-degenerate* groups G_4 *"of type E_7"* relevant for (super)gravities whose (vector multiplets') scalar manifold is a *symmetric* space. In the *triality-symmetric stu* model of $\mathcal{N} = 2$ supergravity, we explicitly construct a basis for the 10 linearly independent degree-12 invariant polynomials of 3-centered black holes.

Contents

1 Introduction

The *Attractor Mechanism* [1, 2], originally discovered in $\mathcal{N} = 2$, $D = 4$ Maxwell-Einstein supergravity and then investigated in other extended supergravities as well as in non-supersymmetric theories of gravity (see *e.g.* [3] for reviews and list of Refs.), plays a central role in the physics of extremal black holes (BHs), as well as of (intersecting configurations of) extremal black p-branes [4], also in $D > 4$ space-time dimensions. In its simplest framework, namely in presence of Abelian vectors and scalar fields in the background of an extremal BH, the area of the event horizon can be expressed purely in terms of the fluxes of the 2-form Abelian field strengths and of their duals, whose fluxes define the magnetic and electric BH charges, fitting a symplectic vector Q. The dynamics of the scalar fields exhibits an *attractor* phenomenon, namely the value of the field at the BH event horizon is completely determined in terms of the magnetic and electric charges, *regardless* of the initial (boundary) conditions defined for the flow at spatial infinity[1]. In general, the near-horizon attractor dynamics can be reformulated in terms of critical points of a *BH effective potential* [2], which in presence of an underlying local supersymmetry also enjoys a geometric interpretation in terms of *central charge*(s) and *matter charges* (if any).

The vector space of electric-magnetic BH charges generally defines an irreducible[2] representation (irrep.) space R for the generalized electric-magnetic (U-) duality[3] group G_4. Under the action of G_4, the irrep. space R undergoes a *stratification* into orbits, which in turn are in correspondence with classes of BHs, with both regular and vanishing near-horizon geometry (corresponding to *"large"* and *"small"* BHs, respectively); thus, the classification of G_4-orbits in R results in a group-theoretical characterization of BH solutions themselves. In Maxwell-Einstein supergravity theories whose scalar manifold is a *symmetric* space G_4/H_4 (with H_4 being the maximal compact subgroup of G_4), the classification of orbits can be algebraically achieved in terms of constraints imposed on the *unique* [9] algebraically independent G_4-invariant homogeneous polynomial $\mathcal{I}$ in the irrep. R (see *e.g.* [10], as well as [11] for a recent *résumé* and a list of Refs.).

Within this rather broad class of $D = 4$ theories, $\mathcal{I}$ is a *quadratic* polynomial ($\mathcal{I} = \mathcal{I}_2$) for $\mathcal{N} = 2$ *minimally coupled* [12, 13] as well as for $\mathcal{N} = 3$ [14] supergravity. In the remaining $D = 4$ theories with *symmetric* scalar manifolds, G_4 can be characterized (in terms of R) as a group *"of type E_7"* [15, 16, 17, 18, 19, 20]. In particular, the charge representation R satisfies

$$\dim \wedge^2 R = \dim S^4 R = 1. \tag{1.1}$$

Namely, the flux irrep. R is *symplectic* (*i.e.*, endowed with a unique symplectic structure $\mathbb{C}_{[MN]} := \mathbf{1} \in \wedge^2 R =: R_a^{\otimes 2}$, as it generally holds in $D = 4$), and it exhibits a unique, algebraically independent, degree-4 homogeneous invariant polynomial[4] $\mathcal{I} = \mathcal{I}_4$, related to a rank-4 completely symmetric G_4-invariant tensor (the so-called K-tensor [21, 22, 23, 24]) $K_{(MNPQ)} := \mathbf{1} \in S^4 R =: R_s^{\otimes 4}$. Simple and semi-simple *non-degenerate* U-duality groups G_4 "of type E_7" relevant to the class of $D = 4$ Maxwell-Einstein (super)gravity theories under consideration are listed in Table 1 at the start of Sec. 2.3.

The properties of the quartic polynomial $\mathcal{I}_4$ constructed from the K-tensor have been exploited in order to characterize in an algebraic way the various scalar flows in the background of extremal *single-centered* BHs [10]. The classification can be extended to *multi-centered* BHs [25, 26, 27, 28, 29, 30, 31].

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[1]Some exception/violations of the *Attractor Mechanism* include *e.g.* the existence of *basins of attraction/area codes* [5] as well as of *moduli spaces/flat directions* of attractor flows [6, 4].

[2]This strictly holds for *unified* theories, in which *all* Abelian 2-form field strengths (and their duals) transform in an irrep. of G_4; the following reasoning can be easily generalized to *non-unified* frameworks.

[3]Here U-duality is referred to as the "continuous" symmetries of [7]. Their discrete versions are the U-duality non-perturbative string theory symmetries introduced by Hull and Townsend [8].

[4]Actually, this characterizes G_4 (which can be simple or semi-simple) as a *non-degenerate* group "of type E_7". The *"degeneration"* of the U-duality symmetry in some $\mathcal{N} = 2$ theories [12, 13] and in $\mathcal{N} = 3$ [14] supergravity, and its relation to the *minimal coupling* of vector and scalar fields in Maxwell-Einstein (super)gravity theories in $D = 4$ has recently been investigated in [19].

In the case of 2-centered solutions, a group theoretical study of the invariant structures which can be defined in the vector space of electric-magnetic fluxes has been started in [32], and then developed in [22, 23, 24, 20]; the connection between 2-centered invariant structures for the so-called *stu* model [33] of $\mathcal{N} = 2$, $D = 4$ supergravity and *Quantum Information Theory* has then been investigated in [34]. Furthermore, relations between the K-tensor of the *stu* model (giving rise to the so-called *Cayley's hyperdeterminant* [36, 37]) and elliptic curves has been recently studied in [38], and extended to the 2-centered case in [34].

Besides the importance of the *symplectic product* $\mathcal{W}$ (see Eq. (2.17) below) in order to define *mutually non-local* charge vectors pertaining to different centers [25], the physical relevance of some higher-order U-invariant polynomials has been suggested in recent investigations [30], and further study in such a direction is surely deserved in order to unravel their role *e.g.* in the spatial structure of general stationary *almost-BPS* [27, 29, 31] and *composite non-BPS* [29, 30, 31] multi-centered BH flows, with *flat* $D = 3$ spatial slices as well as *non-flat* ones [28, 39, 40].

In the case of BH solutions with p centers, the U-duality group G_4 acts on p copies of R; correspondingly, the charge vectors Q^a carry an index referring to the relevant center ($a = 1, ..., p$), and one has to consider polynomial invariants in the $p \dim R$ coordinates on R^p. Thus, a *"horizontal"* symmetry[5] $SL_h(p, \mathbb{R})$, commuting with G_4, naturally occurs. This was firstly introduced in [32], and it acts on the index labelling the various centers, in such a way that G_4-invariant polynomials generally decompose into $SL_h(p, \mathbb{R})$-irreps. In the 2-centered case ($p = 2$), as mentioned, the problem of determining a complete basis for the ring of $(SL_h(p, \mathbb{R}) \times G_4)$-invariant homogeneous polynomials has been solved in [32] and [22], respectively for semi-simple and simple non-degenerate groups "of type E_7" occurring as U-duality groups in $D = 4$ supergravities with symmetric scalar manifolds[6]. Actually, the same results had been obtained, within a completely different approach based on nilpotent orbits, by Kac many years ago in [9]; therein, it was also shown that the complete basis composed by polynomials whose homogeneity degree is the lowest possible is also *finitely generating*, namely all other higher-order invariant polynomials are simply polynomials in the elements of the basis.

For example, in the 2-centered *simple* case [9, 22] there are 7 algebraically independent U-invariant polynomials, which form a minimal degree complete basis for the corresponding ring; out of them, 5 are homogeneous of degree 4 and they are arranged into a **5** (spin $s = 2$) irrep. of the 2-centered "horizontal" symmetry $SL_h(2, \mathbb{R})$, while the remaining ones are polynomials homogeneous of degree 2 and 6 that are $SL_h(2, \mathbb{R})$-invariant (the one of degree 2 is nothing but the *symplectic product* $\mathcal{W}$ defined in (2.17) below). Out of these 7 G_4-invariants, one can construct 4 algebraically independent $(SL_h(2, \mathbb{R}) \times G_4)$-invariant polynomials, homogeneous of degree 2, 6, 8 and 12 [9, 22]. With some abuse of language, $(SL_h(p, \mathbb{R}) \times G_4)$-invariants have been usually named "horizontal" invariants.

In the (2-centered) *semi-simple* case [9, 32, 24], further lower-order horizontal invariant structures arise as a consequence of the factorization of the U-duality symmetry G_4; a particular, noteworthy example is provided by the aforementioned *stu* model, exhibiting a *triality symmetry* [33], which should be modded out in order to obtain invariant structures relevant for BHs (*cfr.* the treatment of [32] *vs.* [34], as well as the treatment in Secs. 2.3.5 and 4.3.4).

Although some general properties can be inferred from elementary group theoretical considerations, a systematic study and classification of ($p > 2$)-centered solutions in terms of $(SL_h(p, \mathbb{R}) \times G_4)$-orbits is still lacking.

The aim of the present paper is to start developing some general methods that can be used to determine all invariants associated to p-centered BH solutions, for a generic p. In particular, we will be interested in p-centered horizontal invariants, namely homogeneous $(SL_h(p, \mathbb{R}) \times G_4)$-invariant polynomials on the irrep. $\mathbb{R}^p \otimes R =: (\mathbf{p}, R)$ of the overall symmetry $SL_h(p, \mathbb{R}) \times G_4$ itself. The invariant polynomials homogeneous of degree k are clearly related to the $(SL_h(p, \mathbb{R}) \times G_4)$-invariant tensors in

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[5]The subscript "h" stands for *"horizontal"* throughout.

[6]The same problem was solved, for a generic number p of centers, in [41, 24] for simple, *degenerate* groups "of type E_7" occurring in $\mathcal{N} = 2$ *minimally coupled* as well as in $\mathcal{N} = 3$ supergravity in $D = 4$.

the k-th completely symmetric[7] power $S^k(\mathbb{R}^p \otimes R) =: (\mathbf{p}, R)_s^{\otimes k}$. This allows for the exploitation of the *classical invariant theory* (for which we will mainly refer to the book [35]).

The plan of the paper is as follows.

In Sec. 2 we use the representation theory of a product group $\mathcal{G} \times G$ in order to determine the corresponding invariant structures. We first recall some general facts about invariant theory and, in particular, the characterization of the $(\mathcal{G} \times G)$-invariants in the symmetric products $S^k(U \otimes V)$ of the irreps. U and V of $\mathcal{G}$ and G, respectively. By applying these methods to the case $\mathcal{G} = SL_h(p, \mathbb{R})$ and $G = G_4$ relevant to p-centered (BH) solutions in $D = 4$ supergravity, we can then count $(SL_h(p, \mathbb{R}) \times G_4)$-invariants[8] for all relevant *generic*, *simple* cases.

Next, in Sec. 3, we present a geometric analysis of the invariants. We show that in the p-centered case the invariants can be determined by using the *Grassmannian $Gr(p, R)$* of p-planes in R. This Grassmannian is embedded in a projective space by its *Plücker coordinates*, which are global sections of a line bundle L on $Gr(p, R)$. For any positive integer a, the group $GL(R)$, and thus[9]

$$G_4 \subset Sp(R) \subset SL(R) \subset GL(R), \tag{1.2}$$

acts on the sections $\Gamma(Gr(p, R), L^{\otimes a})$. These sections are homogeneous polynomials of degree a in the Plücker coordinates. Our geometric characterization of the $(SL_h(p, \mathbb{R}) \times G_4)$-invariant polynomials, in combination with Bott's theorem [46], shows that all these invariants are given by $(SL_h(p, \mathbb{R}) \times G_4)$-invariant sections. In particular, the $(SL_h(p, \mathbb{R}) \times G_4)$-invariant polynomials are generated by homogeneous polynomials in the Plücker coordinates.

Finally, in Sec. 4, we present an application of the methods developed in Secs. 2 and 3 : in the *semi-simple, triality-symmetric $\mathcal{N} = 2$, $D = 4$ stu* model, we compute a basis for the 10-dimensional vector space of $\left(SL_h(3, \mathbb{R}) \times SL(2, \mathbb{R})^3\right)$-invariant polynomials homogeneous of degree 12 for 3-centered BHs; the physical issue of invariance under the symmetric group S_3, implementing the *triality symmetry* acting on the three copies of $SL(2, \mathbb{R})$ in the U-duality group $G_4 = SL(2, \mathbb{R})^3$, is considered in Secs. 2.3.5 and 4.3.4.

2 Algebraic Approach

2.1 Invariant Theory

In order to tackle the problem of determining the invariants associated to multi-centered BH solutions, we will make use of the *classical invariant theory*. Let us first collect some basic facts on how to find invariants in $U \otimes V$ for the action of the group $GL(U) \times GL(V)$; as mentioned above, we will mainly refer to the book [35], to which we address the reader for further details and a list of Refs.

2.1.1 The Schur Polynomials

A partition λ of an integer $m \in \mathbb{Z}_{>0}$, denoted as $\lambda \vdash m$, is a non-increasing sequence $\lambda = (p_1, \dots, p_N)$ of integers $p_i \in \mathbb{Z}_{\geq 0}$ such that $\sum_{i=1}^N p_i = m$. The number of non-zero elements in λ is denoted by $ht(\lambda) := n$, so $p_i = 0$ for $i > n$.

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[7]The subscript "s" ("a") stands for *symmetric* (*antisymmetric*) throughout.

[8]Up to a certain order, fixed by the available computing power (see analysis in Sec. 2.3).

[9]As also recently discussed in [42], the *maximal* (but generally *non-symmetric*) embedding $G_4 \subset Sp(R)$ (which in supergravity is named *Gaillard-Zumino* [43] embedding) can be regarded as a consequence of the following *Theorem* by Dynkin (Th. 1.5 of [44], more recently discussed *e.g.* in [45]) : every *irreducible* group of unimodular linear transformations of the N-dimensional complex space (namely, a group of transformations which does not leave invariant a proper subspace of such a space) is maximal either in $SL(N)$ (if the group does not have a bilinear invariant), or in $Sp(N)$ (if it has a skew-symmetric bilinear invariant), or in $O(N)$ (if it has a symmetric bilinear invariant). Exceptions to this rule are listed in Table VII of [45].

The *Schur polynomial* S_λ in N variables $x_1, \ldots, x_N$, where $N \geq n := ht(\lambda)$, is the symmetric polynomial, with integral coefficients, defined as the quotient ([35], 2.3.2)

$$S_\lambda(x) := \frac{A_{\lambda+\rho}(x)}{V(x)}, \tag{2.1}$$

where the partition $\lambda + \rho$ is defined as $\lambda + \rho := (p_1 + N - 1, p_2 + N - 2, \ldots, p_N)$, and $A_{\lambda+\rho}(x)$ and $V(x)$ (*Vandermonde determinant*) are two anti-symmetric polynomials in $x_1, \ldots, x_N$, respectively given by

$$A_{(m_1, \ldots, m_N)}(x) := \sum_{\sigma \in S_N} \epsilon_\sigma x_{\sigma(1)}^{m_1} x_{\sigma(2)}^{m_2} \cdots x_{\sigma(N)}^{m_N}, \tag{2.2}$$

where S_N is the group of permutations of N variables and ϵ_σ is the permutation parity, and

$$V(x) := \prod_{1 \leq i < j \leq N} (x_i - x_j). \tag{2.3}$$

Note that $S_\lambda = 0$ if $ht(\lambda) > N$.

As from Th. 1 in [35], 2.3.2, the Schur polynomials S_λ with $\lambda \vdash m$ and $ht(\lambda) \leq N$ are a basis of the polynomials in N variables which are homogeneous of degree m and are invariant under permutations of the variables $x_1, \ldots, x_N$. Examples are provided by the elementary symmetric functions

$$S_{1^h} = \sum_{1 \leq i_1 < \ldots < i_h \leq N} x_{i_1} x_{i_2} \cdots x_{i_h}, \qquad \lambda = 1^h := (\underbrace{1, \ldots, 1}_{h}, 0, \ldots, 0); \tag{2.4}$$

$$S_k = \sum_{1 \leq i_1 \leq \ldots \leq i_k \leq N} x_{i_1} x_{i_2} \cdots x_{i_k}, \qquad \lambda = k := (k, \underbrace{0, \ldots, 0}_{N-1}), \tag{2.5}$$

which differ only in the possibility to consider or not the same values for at least a pair of indices in the string $i_1, \ldots, i_h$.

2.1.2 Traces of GL-Representations

Let V be a vector space of dimension N with basis $v_1, \ldots, v_N$, and let $y := (y_1, \ldots, y_N) \in (\mathbb{C}^*)^N$ act by $diag(y_1, \ldots, y_N)$ on V.

A partition λ with $ht(\lambda) \leq N$ defines an irreducible representation $S_\lambda(V)$ of $GL(V)$ which is a summand of $\otimes^m V$ where $\lambda \vdash m$ ([35] 9.3.1, (3.1.3)). If $ht(\lambda) > N$, then $S_\lambda(V) = 0$. Moreover, any irreducible representation of $GL(V)$ is isomorphic to an $S_\lambda(V)$ for a unique partition λ with $ht(\lambda) \leq N$ ([35], 9.8.1). The trace of $diag(y_1, \ldots, y_N) \in (\mathbb{C}^*)^N$ (*i.e.* the standard maximal torus of $GL(V)$) on the irreducible representation $S_\lambda(V)$ is the Schur polynomial $S_\lambda(y_1, \ldots, y_N)$. The dimension of the representation associated to the partition $(p_1, \ldots, p_N)$ is ([35], 9.6.2):

$$\dim S_\lambda(V) = \prod_{1 \leq i < j \leq N} \frac{p_i - p_j + j - i}{j - i}, \qquad \lambda = (p_1, \ldots, p_N). \tag{2.6}$$

For instance, $\lambda := 1^h$ defines $S_\lambda(V) := \wedge^h V$ (2.4), the rank-h completely antisymmetric tensor representation of $GL(V)$, which has dimension $\binom{N}{h}$; in particular, the partition $\lambda = 1^N$ selects the one-dimensional determinant representation on $\wedge^N V$ (realized by the Ricci-Levi-Civita symbol $\epsilon_{i_1 \ldots i_N}$). Another example is provided by the partition $\lambda := k := (k, \underbrace{0, \ldots, 0}_{N-1})$, which defines $S_\lambda(V) := S^k V$ (2.5), the k-th symmetric product of V, namely the rank-k completely symmetric tensor representation of $GL(V)$. A basis of $S^k V$ is provided by $v_1^{a_1} \cdots v_N^{a_N}$ with $a_i \geq 0$ and $\sum_{i=1}^N a_i = k$, and the action of y on this basis elements is the multiplication by $y_1^{a_1} \cdots y_N^{a_N}$. Hence, the trace of y on $S^k V$ is the sum

of all monomials in $y_1, \ldots, y_N$ which are homogeneous of degree k. As mentioned, this is the Schur polynomial S_k (2.5), so $tr(y|S^k V) = S_k(y)$. A generating function for these S_k can be obtained by noting that

$$\begin{aligned} & \left(1 + \ldots + y^{a_1} t^{a_1} + \ldots\right) \left(1 + \ldots + y^{a_2} t^{a_2} + \ldots\right) \ldots \left(1 + \ldots + y^{a_N} t^{a_N} + \ldots\right) \\ = \quad & 1 + S_1(y) t + S_2(y) t^2 + \ldots + S_k(y) t^k + \ldots, \end{aligned} \tag{2.7}$$

and it is given by the *Molien formula* ($S_0(y) = 1$; [35], 9.4.3, (4.4.3)):

$$\prod_{j=1}^{N} \frac{1}{1 - y_j t} = \sum_{k=0}^{\infty} S_k(y) t^k. \tag{2.8}$$

2.1.3   Decomposing $S^k(U \otimes V)$

A generalization of the Molien formula (2.8), which yields the decomposition of $S^k(U \otimes V)$ under $GL(U) \times GL(V)$, is provided by the following formula, due to Cauchy. Let[10] $m \leq n$ be two positive integers, then:

$$\prod_{i=1}^{m} \prod_{j=1}^{n} \frac{1}{1 - x_i y_j} = \sum_{\lambda : ht(\lambda) \leq m \leq n} S_\lambda(x_1, \ldots, x_m) S_\lambda(y_1, \ldots, y_n). \tag{2.9}$$

The interpretation of the Cauchy formula (2.9) in terms of characters of representations is given *e.g.* in [35], 9.6.3. Let U and V be vector spaces of dimension m and n respectively, and assume that $m \leq n$. Let $u_1, \ldots, u_m, v_1, \ldots, v_n$ be bases of U, V respectively, and let $x \in (\mathbb{C}^*)^m$, $y \in (\mathbb{C}^*)^n$ act on these spaces by $diag(x_1, \ldots, x_m)$, $diag(y_1, \ldots, y_n)$. The eigenvalues of (x, y) on $U \otimes V$ are then the $x_i y_j$ with $1 \leq i \leq m$ and $1 \leq j \leq n$. Thus, Cauchy formula (2.9) implies that

$$\sum_{k=0}^{\infty} tr((x, y)|S^k(U \otimes V)) t^k = \sum_{\lambda : ht(\lambda) \leq m \leq n} S_\lambda(x) S_\lambda(y) t^{d_\lambda}, \qquad \lambda \vdash d_\lambda. \tag{2.10}$$

Using the bijection between traces of irreducible representations and irreducible characters, it follows that there is an isomorphism of $(GL(U) \times GL(V))$-representations:

$$S^k(U \otimes V) \cong \bigoplus_{\lambda \vdash k, ht(\lambda) \leq m} S_\lambda(U) \otimes S_\lambda(V). \tag{2.11}$$

A particular consequence of the isomorphism (2.11) is that if $\mathcal{G} \times G$ is a subgroup of $GL(U) \times GL(V)$, then the vector space $\left(S^k(U \otimes V)\right)^{\mathcal{G} \times G}$ of $(\mathcal{G} \times G)$-invariants in $S^k(U \otimes V)$ enjoys the following decomposition:

$$\left(S^k(U \otimes V)\right)^{\mathcal{G} \times G} \cong \bigoplus_{\lambda \vdash k, ht(\lambda) \leq m} (S_\lambda(U)^{\mathcal{G}}) \otimes (S_\lambda(V)^{G}), \tag{2.12}$$

since the action of $\mathcal{G} \times G$ on $S_\lambda(U) \otimes S_\lambda(V)$ preserves the factors. Thus, *in order to compute the $(\mathcal{G} \times G)$-invariants, one can compute the $\mathcal{G}$-invariants on all $S_\lambda(U)$ and the G-invariants on all $S_\lambda(V)$, and then combine the results.*

Given a partition $\lambda = (p_1, \ldots, p_N)$, we define an integer $k \in \mathbb{Z}_{\geq 0}$ and a partition μ with $ht(\mu) \leq N - 1$ by

$$\lambda = (k, \ldots, k) + (k_1, \ldots, k_{N-1}, 0) := (k^N) + \mu. \tag{2.13}$$

Then, the restriction of $S_\lambda(V)$ to $SL(V)$ is isomorphic to $S_\mu(V)$, since (k^N) is the k-th tensor product of the determinant representation. *Ça va sans dire*, if $ht(\lambda) > n$, then the definition of $S_\lambda(V)$ shows that it is the 0-dimensional vector space.

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[10] The formula (2.9) is proven in [35], 2.3.4 for $n = m$, but setting $x_i = 0$ for $m \leq i \leq n$, the proof holds for $m \leq n$.

2.2 Application to p-centered Black Holes

As in Sec. 1, let G_4 be the U-duality group acting on the representation R in which the (fluxes of the) Abelian 2-form field strengths and their duals sit, in the background of a p-centered black hole solution in the corresponding $D = 4$ Maxwell-Einstein (super)gravity theory. Since the *"horizontal"* [32] group $SL_h(p) \equiv SL_h(p, \mathbb{R})$ acts on the labels of the centers, in order to determine the invariants associated to the p-centered BH one has to compute the invariants of $\mathcal{G} \times G = SL_h(p) \times G_4$ on $U \otimes V = \mathbb{R}^p \otimes R =: (\mathbf{p}, R)$.

The representation $S_\lambda(U)$, where $U = \mathbb{R}^p$, of $\mathcal{G} = SL_h(p)$, is irreducible (if non-zero), and there are very few cases in which it is the trivial 1-dimensional representation. In fact, recall that $S_\lambda(V) = 0$ if $ht(\lambda) > p$, whereas if $ht(\lambda) < p$ then $S_\lambda(V)$ is an irreducible representation of $GL(V)$, and hence also of $SL(V)$. Thus $S_\lambda(V)^{\mathcal{G}} = 0$, unless $S_\lambda(V)$ is a power of the 1-dimensional determinant representation of $GL(V)$; namely, unless the partition reads $\lambda = (a, \ldots, a) =: (a^p)$, in which case one has

$$U = \mathbb{R}^p \text{ of } \mathcal{G} = SL_h(p) : \dim\left(S_\lambda(U)^{SL_h(U)}\right) = 1 \quad \Longleftrightarrow \quad \lambda = (a^p) = \underbrace{(a, \ldots, a)}_{p} \tag{2.14}$$

for some $a \in \mathbb{Z}_{\geq 0}$, and $\dim\left(S_\lambda(U)^{SL_h(U)}\right) = 0$ otherwise.

In virtue of formula (2.12), this implies that the invariants of $SL_h(p) \times G_4$ in $S^k(\mathbb{R}^p \otimes R)$ must come from the invariants of G_4 in $S_\lambda(R)$ where $\lambda = (a^p)$. As $(a^p) \vdash pa$, it thus also follows[11]

$$\dim\left(S^{pa}(\mathbb{R}^p \otimes R)^{SL_h(p) \times G_4}\right) = \dim\left(S_{(a^p)}(R)^{G_4}\right), \tag{2.15}$$

and *there are no invariants[12] in $S^k(\mathbb{R}^p \otimes R)$ if k is not a multiple of p*. So, if one has a degree-k $(SL_h(p) \times G_4)$-invariant homogeneous polynomial in the representation $\mathbb{R}^p \otimes R$, then k is a multiple of p (the converse surely does not hold; see *e.g.* Tables (2.31), (2.38), (2.40), (2.42) and (2.45) below).

Before explicitly analyzing some cases relevant to supergravity, let us consider the lowest degrees of homogeneity : $k = 2$ and $k = 3$.

2.2.1 Homogeneity $k = 2$

In the case $k = 2$, the partitions λ with $\lambda \vdash 2$ are $\lambda = (2, 0) =: 2$ and $\lambda = (1, 1) =: 1^2$. Since $S_2(V) = S^2V$ and $S_{1^2} = \wedge^2 V$, one obtains (provided $ht(\lambda) \leq 2 \leq \min(\dim U, \dim V)$):

$$S^2(U \otimes V) \cong (S^2U) \otimes (S^2V) \oplus (\wedge^2U) \otimes (\wedge^2V). \tag{2.16}$$

A particular case, in which the term $(S^2U) \otimes (S^2V)$ does not yield any invariant, is provided by 2-centered $(p = 2)$ BHs in the framework under consideration, namely for $p = 2$: $U \otimes V = \mathbb{R}^2 \otimes R$ of $\mathcal{G} \times G = SL_h(2, \mathbb{R}) \times G_4$. As both $SL_h(2, \mathbb{R})$ and G_4 have an invariant in $\wedge^2 \mathbb{R}^2 \cong \mathbb{R}$ and in $\wedge^2 R$, respectively (namely, both the fundamental spin $s = 1/2$ irrep. $\mathbf{2}$ of $SL_h(2, \mathbb{R})$ and the irrep. R of G_4 are *symplectic*) one obtains one invariant from the term $(\wedge^2U) \otimes (\wedge^2V)$ of (2.16), given by the *symplectic product* $\mathcal{W}$ in R of G_4, namely [32, 22, 24] $(a, b = 1, 2, M, N = 1, \ldots, \dim R)$:

$$\mathcal{W} := (Q_1, Q_2) := \mathbb{C}_{MN} Q_1^M Q_2^N = \frac{1}{2} \epsilon^{ab} \mathbb{C}_{MN} Q_a^M Q_b^N, \tag{2.17}$$

where ϵ^{ab} is the Ricci-Levi-Civita symbol of $SL_h(2, \mathbb{R})$. When $\mathcal{W} \neq 0$, the charge vectors Q_1 and Q_2 (respectively pertaining to BH centers 1 and 2) are *mutually non-local*, and the distance between the

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[11]In Sec. 3.1 we will discuss in some detail the G_4-representation $S_{(a^p)}(R)$ which gives rise to all invariants.

[12]Besides the above reasoning, another proof of this fact is the following one : the group $SL(p, \mathbb{C})$ contains the matrices λI where $\lambda = e^{2\pi i/p}$, and the element $(\lambda I, I) \in SL(p) \times G_4$ acts as multiplication by the scalar λ on $\mathbb{C}^p \otimes R$, and hence by λ^k on $S^k(\mathbb{C}^p \otimes R)$.

two centers in the BPS 2-centered system is fixed [25]. No other algebraically independent invariant polynomial homogeneous of degree $k = 2$ arise, since the representations $U = \mathbb{R}^2 =: \mathbf{2}$ of $SL_h(2,\mathbb{R})$ and $V = R$ of G_4 are irreducible, and thus there are no other invariants in $S^2 U$ and in $S^2 V$.

As discussed at the end of Sec. 3 of [22], some $SL_h(p,\mathbb{R})$-covariant structures for $p \geqslant 3$ can be directly inferred from the 2-centered ones. Indeed, the 2-centered representation of spin $s = J/2$ of $SL_h(2,\mathbb{R})$ is in general replaced by the completely symmetric rank-J tensor representation[13] $S^J \mathbf{p}$ of $SL_h(p,\mathbb{R})$. On the other hand, for p centers $\mathcal{W}$ (2.17) generally sits in the $\left(\wedge^2 \mathbf{p}, \mathbf{1}\right)$ of $SL_h(p,\mathbb{R}) \times G_4$, where $\wedge^2 \mathbf{p}$ is the rank-2 antisymmetric tensor representation[14] (which, in the case $p = 2$, becomes a singlet).

2.2.2 Homogeneity $k = 3$ for $G_4 = E_7$

In the case $k = 3$, the partitions λ with $\lambda \vdash 3$ are $\lambda = (3,0,0) =: 3$, $\lambda = (2,1,0) =: (2,1)$ and $\lambda = (1,1,1) =: 1^3$. Since $S_3(V) = S^3 V$ and $S_{1^3} = \wedge^3 V$, the $GL(V)$-representation $S_{(2,1)}(V)$ is obtained by the decomposition[15] (*cfr. e.g.* [35], 9.3.1)

$$V^{\otimes 3} := V \otimes V \otimes V \cong \left(S^3 V\right) \oplus \left(S_{(2,1)}(V)\right)^{\oplus 2} \oplus \wedge^3 V. \tag{2.18}$$

The simplest example is provided once again by $V = \mathbb{R}^2 =: \mathbf{2}$ of $SL_h(2,\mathbb{R})$, for which it holds

$$\mathbf{2} \otimes \mathbf{2} \otimes \mathbf{2} \cong (\mathbf{3} \oplus \mathbf{1}) \otimes \mathbf{2} \cong (\mathbf{4} \oplus \mathbf{2}) \oplus \mathbf{2}, \tag{2.19}$$

where $\mathbf{4} =: S^3 V$ is the spin $s = 3/2$ of $SL_h(2,\mathbb{R})$ itself, consistent with the Clebsch-Gordan formula for this group.

Another example, in which we also exploit the physicists' notation of representations by means of their dimension, is provided by $V = V(\lambda_7) =: \mathbf{56}$ (fundamental) irrep. of $G_4 = E_7$. In this case, the following decomposition holds[16]:

$$\begin{array}{rcl} \underset{(\mathbf{56} \otimes \mathbf{56} \otimes \mathbf{56})_s}{S^3 V(\lambda_7)} & \cong & \underset{\mathbf{24320}}{V(3\lambda_7)} \oplus \underset{\mathbf{6480}}{V(\lambda_1 + \lambda_7)} \oplus \underset{\mathbf{56}}{V(\lambda_7)}; \end{array} \tag{2.20}$$

$$\begin{array}{rcl} \underset{(\mathbf{56} \otimes \mathbf{56} \otimes \mathbf{56})_a}{\wedge^3 V(\lambda_7)} & \cong & \underset{\mathbf{27664}}{V(\lambda_5)} \oplus \underset{\mathbf{56}}{V(\lambda_7)}. \end{array} \tag{2.21}$$

On the other hand:

$$\underset{\mathbf{56} \otimes \mathbf{56}}{V^{\otimes 2}} := V \otimes V \cong \underset{(\mathbf{56} \otimes \mathbf{56})_s}{\left(S^2 V\right)} \oplus \underset{(\mathbf{56} \otimes \mathbf{56})_a}{\wedge^2 V} = (\underset{\mathbf{1463}}{V(2\lambda_7)} \oplus \underset{\mathbf{133}}{V(\lambda_1)}) \oplus (\underset{\mathbf{1539}}{V(\lambda_6)} \oplus \underset{\mathbf{1}}{V(0)}). \tag{2.22}$$

Thus, tensoring once more with $V(\lambda_7)$, one obtains

$$\begin{array}{rcl} \underset{\mathbf{1463} \otimes \mathbf{56}}{V(2\lambda_7) \otimes V(\lambda_7)} & \cong & \underset{\mathbf{24320}}{V(3\lambda_7)} \oplus \underset{\mathbf{51072}}{V(\lambda_6 + \lambda_7)} \oplus \underset{\mathbf{6480}}{V(\lambda_1 + \lambda_7)} \oplus \underset{\mathbf{56}}{V(\lambda_7)}; \end{array} \tag{2.23}$$

$$\begin{array}{rcl} \underset{\mathbf{1539} \otimes \mathbf{56}}{V(\lambda_6) \otimes V(\lambda_7)} & \cong & \underset{\mathbf{51072}}{V(\lambda_6 + \lambda_7)} \oplus \underset{\mathbf{27664}}{V(\lambda_5)} \oplus \underset{\mathbf{6480}}{V(\lambda_1 + \lambda_7)} \oplus \underset{\mathbf{912}}{V(\lambda_2)} \oplus \underset{\mathbf{56}}{V(\lambda_7)}; \end{array} \tag{2.24}$$

$$\begin{array}{rcl} \underset{\mathbf{133} \otimes \mathbf{56}}{V(\lambda_1) \otimes V(\lambda_7)} & \cong & \underset{\mathbf{6480}}{V(\lambda_1 + \lambda_7)} \oplus \underset{\mathbf{512}}{V(\lambda_2)} \oplus \underset{\mathbf{56}}{V(\lambda_7)}. \end{array} \tag{2.25}$$

---

[13]In the case of $GL(p,\mathbb{R})$, this is given by $S_\lambda(V)$ (2.5) with $V = \mathbb{R}^p =: \mathbf{p}$ and $\lambda := J := (J, \underbrace{0, \ldots, 0}_{p-1})$; see below (2.6).

The same holds for $SL(p,\mathbb{R})$.

[14]In the case of $GL(p,\mathbb{R})$, this is given by $S_\lambda(V)$ (2.4) with $V = \mathbb{R}^p =: \mathbf{p}$ and $\lambda := 1^2$; see below (2.6). The same holds for $SL(p,\mathbb{R})$.

[15]This is generalized to $V^{\otimes n}$ (for a generic n) *e.g.* in [35], 9.3.1.

[16]The weights/roots standard notation of irreps. is used throughout.

Thus, (2.18) and (2.20)-(2.25) yield

$$S_{(2,1)}\left(V\left(\lambda_7\right)\right) \cong \underset{\mathbf{51072}}{V\left(\lambda_6+\lambda_7\right)} \oplus \underset{\mathbf{6480}}{V\left(\lambda_1+\lambda_7\right)} \oplus \underset{\mathbf{912}}{V\left(\lambda_2\right)} \oplus \underset{\mathbf{56}}{V\left(\lambda_7\right)}. \tag{2.26}$$

Therefore, we obtained that

$$\underset{\mathbf{1}}{V\left(0\right)} \notin \left\{ \begin{array}{l} S^3 V\left(\lambda_7\right); \\ S_{(2,1)}\left(V\left(\lambda_7\right)\right); \\ \wedge^3 V\left(\lambda_7\right), \end{array} \right. \tag{2.27}$$

and thus there are no E_7-invariants in $S_\lambda\left(V\left(\lambda_7\right)\right)$ if $\lambda \vdash 3$. More in general, *there are no E_7-invariants on $V\left(\lambda_7\right)^{\otimes n}$ for n odd.* Since $S_\lambda\left(V\right) \subset V^{\otimes n}$ when $\lambda \vdash n$, it follows that there are no E_7-invariants in $S_\lambda\left(V\left(\lambda_7\right)\right)$ when λ is a partition of an *odd* (positive) integer n.

In other words, *there are no invariant polynomials in the fundamental representation $V\left(\lambda_7\right) =: \mathbf{56}$ of E_7 with an odd homogeneity degree*, as also confirmed by the treatment of Sec. 2.3.1; more in general, this will hold *at least* for all the (simple and semi-simple) groups "of type E_7" which we will consider : *there are no invariant polynomials in the relevant irrep. R of G_4 with an odd homogeneity degree*[17].

2.3 Examples

We now consider explicit examples, relevant for p-centered ($p \geqslant 2$) black holes in some $D = 4$ Maxwell-Einstein (super)gravity theories, with generalized electric-magnetic (U-)duality group G_4; as done above, we denote the relevant G_4-representation in which the (fluxes of the) Abelian 2-form field strengths (and their duals) sit by[18] $V = R$, and we will specify it case by case.

In particular, we here consider the class of groups "of type E_7" [15] which can be characterized as conformal groups of rank-3, *simple* Euclidean Jordan algebras $J_3^{\mathbb{A}}$ or $J_3^{\mathbb{A}_s}$, or equivalently as the automorphism group of the Freudenthal triple system (FTS) $\mathfrak{M}\left(J_3\right)$ constructed over such algebras [49]:

$$G_4 = Conf\left(J_3\right) = Aut\left(\mathfrak{M}\left(J_3\right)\right). \tag{2.28}$$

$\mathbb{A}$ denotes the division algebras $\mathbb{A} = \mathbb{O}, \mathbb{H}, \mathbb{C}, \mathbb{R}$, while $\mathbb{A}_s$ denotes the corresponding split composition algebras $\mathbb{A}_s = \mathbb{O}_s, \mathbb{H}_s, \mathbb{C}_s, \mathbb{R}$. The representation R pertains to $\mathfrak{M}\left(J_3\right)$, and its dimension is $6q + 8$, where the parameter $q = \dim_{\mathbb{R}} \mathbb{A}_{(s)} = 8, 4, 2, 1$ for $\mathbb{A}_{(s)} = \mathbb{O}_{(s)}, \mathbb{H}_{(s)}, \mathbb{C}_{(s)}, \mathbb{R}$, respectively. These class of groups "of type E_7" has been recently studied as U-duality symmetries in the context of $D = 4$ locally supersymmetric theories of gravity in [17, 18, 19], as well as gauge (and global) symmetries in particular $D = 3$ gauge theories [42].

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[17]The reason can be traced back to the fact that $-I$ on R belongs to G_4. For instance, it can be checked that the $-I$ in the $\mathbf{56}$ of E_7 preserves the symplectic metric $\mathbb{C}_{[MN]}$ in $\mathbf{56}_a^{\otimes 2}$ and the quartic symmetric tensor $K_{(MNPQ)}$ in $\mathbf{56}_s^{\otimes 4}$ ($M, N, P, Q = 1, .., 56$).

[18]It is worth pointing out that the irrep. R is real for the very non-compact real forms of G_4 pertaining to the relevant U-duality groups, while usually for the other (non-compact) real forms it is pseudo-real (quaternionic). This reality property can *e.g.* be inferred from the corresponding (symmetric) embeddings into G_3, the relevant U-duality symmetry in $D = 3$ space-time dimensions.

As an example, let us consider the fundamental representation $R = \mathbf{56}$ of E_7 : it is real for the relevant non-compact real forms $E_{7(7)}$ (*split*) and $E_{7(-25)}$ (minimally non-compact), while it is pseudo-real (quaternionic) for $E_{7(-133)}$ and $E_{7(-5)}$. Indeed, while $E_{7(7)}$ and $E_{7(-25)}$ respectively embed into $E_{8(8)}$ and $E_{8(-24)}$ through a $SL(2, \mathbb{R})$ commuting factor:

$$E_{8(8)} \supset E_{7(7)} \times SL(2, \mathbb{R}), \quad E_{8(-24)} \supset E_{7(-25)} \times SL(2, \mathbb{R}),$$

$E_{7(-133)}$ and $E_{7(-5)}$ embed into $E_{8(-24)}$ and $E_{8(8)}$ through an $SU(2)$ factor:

$$\begin{aligned} E_{8(-24)} &\supset E_{7(-133)} \times SU(2), \quad E_{8(-24)} \supset E_{7(-5)} \times SU(2); \\ E_{8(8)} &\supset E_{7(-5)} \times SU(2). \end{aligned}$$

J_3	G_4	R	$\mathcal{N}$
$J_3^{\mathbb{O}}$, $J_3^{\mathbb{O}_s}$	$E_{7(-25)}$, $E_{7(7)}$	**56**	2, 8
$J_3^{\mathbb{H}}$, $J_3^{\mathbb{H}_s}$	$SO^*(12)$, $SO(6,6)$	$\mathbf{32}^{(\prime)}$	2 or 6, 0
$J_3^{\mathbb{C}}$, $J_3^{\mathbb{C}_s}$, $M_{1,2}(\mathbb{O})$	$SU(3,3)$, $SL(6,\mathbb{R})$, $SU(1,5)$	**20**	2, 0, 5
$J_3^{\mathbb{R}}$	$Sp(6,\mathbb{R})$	$\mathbf{14'}$	2
$\mathbb{R}$ (t^3 model)	$SL(2,\mathbb{R})$	**4**	2
$R \oplus \mathbf{\Gamma}_{m-1,n-1}$	$SL(2,\mathbb{R}) \times SO(m,n)$	$(\mathbf{2},\mathbf{m+n})$	2 (m or $n = 2$) 4 (m or $n = 6$) 0 otherwise

Table 1: Simple and semi-simple, *non-degenerate* U-duality groups G_4 "of type E_7" [15]. The relevant symplectic irrep. R of G_4 is also reported. Note that the G_4 related to split composition algebras $\mathbb{O}_s$, $\mathbb{H}_s$, $\mathbb{C}_s$ is the *maximally non-compact* (*split*) real form of the corresponding compact Lie group. The corresponding scalar manifolds are the *symmetric* spaces $\frac{G_4}{H_4}$, where H_4 is the maximal compact subgroup (with symmetric embedding) of G_4. The number of supercharges $\mathcal{N}$ of the resulting supergravity theory in $D = 4$ is also listed. The $D = 5$ uplift of the t^3 model (based on $J_3 = \mathbb{R}$) is the *pure* $\mathcal{N} = 2$, $D = 5$ supergravity. $J_3^{\mathbb{H}}$ is related to both 8 and 24 supersymmetries, because the corresponding supergravity theories share the very same bosonic sector [47, 48, 13].

An exception is provided by the *stu* model [33] (Sec. 2.3.5), whose *triality symmetry* is exploited within a particular case in Sec. 4.

From Sec. 2.2, it is here worth recalling that in general *there are no polynomial invariants of* $(\mathbf{p}, R)$ *of* $SL_h(p,\mathbb{R}) \times G_4$ *with homogeneity degree* k *if* k *is not a multiple of* p.

2.3.1 $G_4 = E_7$, $R = \mathbf{56}$

This is the prototypical case of groups "of type E_7" [15]. In supergravity, this is related to the $D = 4$ theories with symmetric scalar manifold, based on the FTS $\mathfrak{M}\left(J_3^{\mathbb{O}}\right)$ (exceptional $\mathcal{N} = 2$ Maxwell-Einstein theory, with $G_4 = E_{7(-25)}$ [47]) and $\mathfrak{M}\left(J_3^{\mathbb{O}_s}\right)$ ($\mathcal{N} = 8$ maximal supergravity, with $G_4 = E_{7(7)}$ [7, 50]), where $J_3^{\mathbb{O}}$ and $J_3^{\mathbb{O}_s}$ are rank-3 Euclidean Jordan algebras over the octonions $\mathbb{O}$ and split octonions $\mathbb{O}_s$, respectively.

The dimension $\dim S_{(a^p)}(R)^{E_7}$ for the partition $\lambda = a^p$ and $R = V(\lambda_7) =: \mathbf{56}$ (fundamental irrep.) can be computed *e.g.* by using the software LiE [51], typing the command[19]

$$\texttt{plethysm([a,\ldots,a],[0,0,0,0,0,0,1],E7)[1]}. \tag{2.29}$$

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[19]In LiE, one first increases the maximal size by typing the command "`maxobjects 99999999`".

The "[1]" at the end corresponds to the lowest representation. The output of the command is an integer, which we denote by d, times $X[b_1, \ldots, b_7]$, where $X[b_1, \ldots, b_7]$ indicates the representation with highest weight $b_1\lambda_1 + \cdots + b_7\lambda_7$, the λ_i being the fundamental weights $(i = 1, ..., 7)$. If all b_i's are zero, then one has found polynomial invariants of homogeneity degree pa in $p \dim R = 56p$ variables; the real dimension of the vector space of such invariants is given by (recall (2.15))

$$\dim [S_{\lambda=a^p} (V(\lambda_7))]^{E_7} = \dim [S^{pa}(p, V(\lambda_7))]^{SL_h(p,\mathbb{R}) \times E_7} = \dim [S^{pa}(\mathbf{p}, \mathbf{56})]^{SL_h(p,\mathbb{R}) \times E_7} =: d. \quad (2.30)$$

By perusing the first few a's for the first few p's, one gets the following table[20]:

E_7, $\mathbf{56}$	$a =$	0	1	2	3	4	5	6	7	8	9	10
$p = 2$	$d =$	1	1	1	2	3	3	5	6	7	9	11
$p = 3$	$d =$	1	0	0	0	5	0	1	0	46		
$p = 4$	$d =$	1	1	1	4	14	35					
$p = 5$	$d =$	1	0	0	0	31						
$p = 6$	$d =$	1	1	2	10							
$p = 7$	$d =$	1	0	2								
$p = 8$	$d =$	1	1									

$$(2.31)$$

(throughout the treatment, the blank entries are seemingly not accessible with the computing facilities available to us.)

In the 2-centered case $(p = 2)$, $\dim S_{1^2}(\mathbf{56})^{E_7} = 1$ corresponds to $\mathcal{W}$ (2.17). The interpretation of the other results is as follows:

$$\dim S_{2^2}(\mathbf{56})^{E_7} = 1 \quad : \quad \mathcal{W}^2$$
$$\dim S_{3^2}(\mathbf{56})^{E_7} = 2 \quad : \quad \mathcal{W}^3, \ \mathbf{I}_6$$
$$\dim S_{4^2}(\mathbf{56})^{E_7} = 3 \quad : \quad \mathcal{W}^4, \ \mathbf{I}_6\mathcal{W}, \ \mathrm{Tr}\left(\mathbf{I}^2\right)$$
$$\dim S_{5^2}(\mathbf{56})^{E_7} = 3 \quad : \quad \mathcal{W}^5, \ \mathbf{I}_6\mathcal{W}^2, \ \mathrm{Tr}\left(\mathbf{I}^2\right)\mathcal{W}$$
$$\dim S_{6^2}(\mathbf{56})^{E_7} = 5 \quad : \quad \mathcal{W}^6, \ \mathbf{I}_6^2, \ \mathrm{Tr}\left(\mathbf{I}^2\right)\mathcal{W}^2, \ \mathrm{Tr}\left(\mathbf{I}^3\right), \ \mathbf{I}_6\mathcal{W}^3$$
$$\dim S_{7^2}(\mathbf{56})^{E_7} = 6 \quad : \quad \mathcal{W}^7, \ \mathbf{I}_6^2\mathcal{W}, \ \mathbf{I}_6\mathrm{Tr}\left(\mathbf{I}^2\right), \ \mathrm{Tr}\left(\mathbf{I}^3\right)\mathcal{W}, \ \mathrm{Tr}\left(\mathbf{I}^2\right)\mathcal{W}^3, \ \mathbf{I}_6\mathcal{W}^4$$
$$\dim S_{8^2}(\mathbf{56})^{E_7} = 7 \quad : \quad \left\{ \begin{array}{l} \mathcal{W}^8, \ \mathbf{I}_6^2\mathcal{W}^2, \ \mathbf{I}_6\mathrm{Tr}\left(\mathbf{I}^2\right)\mathcal{W}, \ \mathrm{Tr}\left(\mathbf{I}^3\right)\mathcal{W}^2, \\ \mathrm{Tr}\left(\mathbf{I}^2\right)\mathcal{W}^4, \ \mathbf{I}_6\mathcal{W}^5, \ \mathrm{Tr}^2\left(\mathbf{I}^2\right) \end{array} \right.$$
$$\dim S_{9^2}(\mathbf{56})^{E_7} = 9 \quad : \quad \left\{ \begin{array}{l} \mathcal{W}^9, \ \mathbf{I}_6^2\mathcal{W}^3, \ \mathbf{I}_6\mathrm{Tr}\left(\mathbf{I}^2\right)\mathcal{W}^2, \ \mathrm{Tr}\left(\mathbf{I}^3\right)\mathcal{W}^3, \\ \mathrm{Tr}\left(\mathbf{I}^2\right)\mathcal{W}^5, \ \mathbf{I}_6\mathcal{W}^6, \ \mathrm{Tr}^2\left(\mathbf{I}^2\right)\mathcal{W}, \ \mathrm{Tr}\left(\mathbf{I}^3\right)\mathbf{I}_6, \ \mathbf{I}_6^3 \end{array} \right.$$
$$\dim S_{10^2}(\mathbf{56})^{E_7} = 11 \quad : \quad \left\{ \begin{array}{l} \mathcal{W}^{10}, \ \mathbf{I}_6^2\mathcal{W}^4, \ \mathbf{I}_6\mathrm{Tr}\left(\mathbf{I}^2\right)\mathcal{W}^3, \ \mathrm{Tr}\left(\mathbf{I}^3\right)\mathcal{W}^4, \ \mathrm{Tr}\left(\mathbf{I}^2\right)\mathcal{W}^6, \\ \mathbf{I}_6\mathcal{W}^7, \ \mathrm{Tr}^2\left(\mathbf{I}^2\right)\mathcal{W}^2, \ \mathrm{Tr}\left(\mathbf{I}^3\right)\mathbf{I}_6\mathcal{W}, \ \mathbf{I}_6^3\mathcal{W}, \ \mathbf{I}_6^2\mathrm{Tr}\left(\mathbf{I}^2\right), \ \mathrm{Tr}\left(\mathbf{I}^2\right)\mathrm{Tr}\left(\mathbf{I}^3\right), \end{array} \right.$$

$$(2.32)$$

where the 2-centered polynomial invariants[21] $\mathbf{I}_6$ (degree 6), $\mathrm{Tr}\left(\mathbf{I}^2\right)$ (degree 8) and $\mathrm{Tr}\left(\mathbf{I}^3\right)$ (degree 12) have been firstly introduced in [32], and then studied in this very case in [22]. Note that no polynomial 2-centered invariants in the $\mathbf{56}$ of E_7 exist with an *odd* homogeneity degree, consistent with the observation made in Sec. 2.2.2. The interpretation (2.32) of the $p = 2$ row of Table (2.31) is an evidence for the fact that the set

$$\left\{ \mathcal{W}, \mathbf{I}_6, \mathrm{Tr}\left(\mathbf{I}^2\right), \mathrm{Tr}\left(\mathbf{I}^3\right) \right\} \quad (2.33)$$

is a complete basis for the ring of polynomial invariants of $(\mathbf{2}, \mathbf{56})$ of $SL_h(2, \mathbb{R}) \times E_7$, and it is *finitely generating*, namely all higher order polynomial invariants are simply polynomials in the polynomials of the set (2.33) itself [9].

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[20]The result $\dim [S_{\lambda=0^p}(V)]^{G_4} = 1$ always trivially refers to a numerical constant.
[21]As discussed at the end of Sec. 3 of [22], for p centers $\mathbf{I}_6$, as $\mathcal{W}$ (2.17), generally sits in the $\left(\wedge^2\mathbf{p}, \mathbf{1}\right)$ of $SL_h(p, \mathbb{R}) \times G_4$.

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In the 3-centered case ($p = 3$), Table (2.31) yields that there are no E_7-invariants for the partitions $\lambda = 1^3$, 2^3, 3^3 and hence there are no polynomial invariants of $(\mathbf{3}, \mathbf{56})$ of $SL_h(3, \mathbb{R}) \times E_7$ with homogeneity degree ≤ 10. The lowest possible degree is 12, at which `Lie` finds 5 invariants. The absence of an invariant corresponding to the partition $\lambda = 1^3$, *i.e.* of a "3-centered analogue" of $\mathcal{W}$ (2.17) can be explained by the fact that $\mathbf{1} \notin \mathbf{56}_a^{\otimes 3}$ (as mentioned, no invariant polynomials in the $\mathbf{56}$ of E_7 with an *odd* homogeneity degree exist at all). Then, one invariant of degree 18, and as many as 46 invariants of degree 24, are found.

In the 4-centered case ($p = 4$), there is an E_7-invariant of degree 4 (the lowest possible degree). It can be regarded as the "4-centered analogue" of $\mathcal{W}$ (2.17), whose existence can be explained by the fact that $\exists! \mathbf{1} \in \mathbf{56}_a^{\otimes 4}$, given by the complete antisymmetrization of the product of two symplectic metrics $\mathbb{C}_{MN}$ of $\mathbf{56}$, such that ($a = 1, ..., 4$, $M = 1, ..., 56$)

$$\dim S_{1^4}(\mathbf{56})^{E_7} = 1 : \mathcal{W}_{p=4} := \frac{1}{4!} \mathbb{C}_{[MN} \mathbb{C}_{PQ]} \epsilon^{abcd} Q_a^M Q_b^N Q_c^P Q_d^Q. \tag{2.34}$$

Thus, $\mathcal{W}_{p=4}$ (2.34) is the unique polynomial invariant of $(\mathbf{4}, \mathbf{56})$ of $SL_h(4, \mathbb{R}) \otimes E_7$ with homogeneity degree 4. Its square yields the unique polynomial invariant of $(\mathbf{4}, \mathbf{56})$ of $SL_h(4, \mathbb{R}) \times E_7$ with homogeneity degree 8, as given by Table (2.31): $\dim S_{2^4}(\mathbf{56})^{E_7} = 1$.

In the 5-centered case ($p = 5$), there are no invariants of degree ≤ 15, since the partitions $\lambda = 1^5$, 2^5 and 3^5 do not yield any invariant for E_7. Once again, the absence of an invariant corresponding to the partition $\lambda = 1^5$, *i.e.* of a "5-centered analogue" of $\mathcal{W}$ (2.17), can be explained by the fact that $\mathbf{1} \notin \mathbf{56}_a^{\otimes 5}$.

Finally, for the $p = 6$ and 8 -centered cases, we see that there is a unique polynomial invariant of $(\mathbf{p}, \mathbf{56})$ of $SL_h(p, \mathbb{R}) \times E_7$ (corresponding to the partition $\lambda = 1^p$); again, for $p = 6$ and 8 it can be regarded as the "p-centered analogue" of $\mathcal{W}$ (2.17), whose existence can be explained by the fact that $\exists! \mathbf{1} \in \mathbf{56}_a^{\otimes 6}$ and $\exists! \mathbf{1} \in \mathbf{56}_a^{\otimes 8}$, given by the complete antisymmetrization of the product of $p = 6, 8$ symplectic metrics $\mathbb{C}_{MN}$ of $\mathbf{56}$, such that

$$\dim S_{1^6}(\mathbf{56})^{E_7} = 1 : \mathcal{W}_{p=6} := \frac{1}{6!} \mathbb{C}_{[MN} \mathbb{C}_{PQ} \mathbb{C}_{RS]} \epsilon^{abcdef} Q_a^M Q_b^N Q_c^P Q_d^Q Q_e^R Q_f^S; \tag{2.35}$$

$$\dim S_{1^8}(\mathbf{56})^{E_7} = 1 : \mathcal{W}_{p=8} := \frac{1}{8!} \mathbb{C}_{[MN} \mathbb{C}_{PQ} \mathbb{C}_{RS} \mathbb{C}_{TU]} \epsilon^{abcdefgh} Q_a^M Q_b^N Q_c^P Q_d^Q Q_e^R Q_f^S Q_g^T Q_h^U, \tag{2.36}$$

where the *"horizontal"* a-indices range over $1, ..., 6$ and $1, ..., 8$ in (2.35) and (2.36), respectively.

2.3.2 $G_4 = Sp(6, \mathbb{R})$, $R = \mathbf{14}'$

In supergravity, this is related to the $D = 4$ theory with symmetric scalar manifold, based on the FTS $\mathfrak{M}(J_3^{\mathbb{R}})$, namely the magic $\mathcal{N} = 2$ Maxwell-Einstein theory over $J_3^{\mathbb{R}}$ (the rank-3 Euclidean Jordan algebras over the reals $\mathbb{R}$ [47]).

In this case, the relevant $Sp(6, \mathbb{R})$-representation is[22] $R = V(\lambda_3) =: \mathbf{14}'$, namely the rank-3 completely antisymmetric skew-traceless representation, which is an irreducible component of $\wedge^3 \mathbf{6} =: \mathbf{6}_a^{\otimes 3}$ (where $\mathbf{6}$ is the fundamental representation). The dimension $\dim S_{(a^p)}(\mathbf{14}')^{Sp(6,\mathbb{R})}$ for the partition $\lambda = a^p$, yielding the (real) dimension of the vector space of polynomial invariants of homogeneity degree pa in $p \dim R = 14p$ variables, is given as above:

$$\dim \left[S_{\lambda=a^p} \left(\mathbf{14}' \right) \right]^{Sp(6,\mathbb{R})} = \dim \left[S^{pa} \left(\mathbf{p}, \mathbf{14}' \right) \right]^{SL_h(p,\mathbb{R}) \times Sp(6,\mathbb{R})} =: d. \tag{2.37}$$

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[22]There are actually two irreducible representations of $Sp(6, \mathbb{R})$ with dimension 14 : the rank-2 antisymmetric skew-traceless $\mathbf{14}$, and the rank-3 antisymmetric skew-traceless $\mathbf{14}'$; this latter characterizes $Sp(6, \mathbb{R})$ as a group "of type E_7" [15].

By perusing the first few a's for the first few p's, one gets the following table:

$Sp(6,\mathbb{R})$, $\mathbf{14}'$	$a=$	0	1	2	3	4	5	6	7	8	9	10
$p=2$	$d=$	1	1	1	2	3	3	5	6	7	9	11
$p=3$	$d=$	1	0	0	0	4	0	0	0	33		
$p=4$	$d=$	1	1	2	5	13	28					
$p=5$	$d=$	1	0	0	0	17						
$p=6$	$d=$	1	1	2	8							
$p=7$	$d=$	1	0	0	0							
$p=8$	$d=$	1	1	2								

(2.38)

Considerations essentially analogous to the ones made for the case of $G_4 = E_7$ and $R = \mathbf{56}$ hold in this case, and in subsequent cases, as well.

Note that the $p = 2$ row of Table (2.38) is identical to the $p = 2$ row of Table (2.31); thus, the structure of the ring of polynomial invariants of $(\mathbf{2}, \mathbf{14}')$ of $SL_h(2,\mathbb{R}) \times Sp(6,\mathbb{R})$ is the very same as the one of $(\mathbf{2}, \mathbf{56})$ of $SL_h(2,\mathbb{R}) \times E_7$. The same will hold for all other examples of groups "of type E_7" relevant to $D = 4$ supergravity which we will consider below, meaning that the structure of two-centered invariants, as well as their interpretation (2.32), is the very same in all these cases.

However, this does not hold any more already starting from the 3-centered case ($p = 3$), as it is immediate to realize by comparing the $p = 3$ rows of (2.31) and (2.38). Indeed, Table (2.38), as Table (2.31), yields that there are no $Sp(6,\mathbb{R})$-invariants for the partitions $\lambda = 1^3$, 2^3, 3^3 and hence there are no polynomial invariants of $(\mathbf{3}, \mathbf{14}')$ of $SL_h(3,\mathbb{R}) \times Sp(6,\mathbb{R})$ with homogeneity degree ≤ 10, the lowest possible degree being 12, at which however Lie finds 4 invariants, instead of 5 invariants as in the E_7 case treated above. As above, the absence of an invariant corresponding to the partition $\lambda = 1^3$, i.e. of a "3-centered analogue" of $\mathcal{W}$ (2.17), can be explained by the fact that $\mathbf{1} \notin \mathbf{14}'^{\otimes 3}_a$.

2.3.3 $G_4 = SO(12)$, $R = \mathbf{32}^{(\prime)}$

This is related to the $D = 4$ theories with symmetric scalar manifold, based on the FTS's $\mathfrak{M}\left(J_3^{\mathbb{H}}\right)$ (magic $\mathcal{N} = 2$ Maxwell-Einstein supergravity, sharing the same bosonic sector of $\mathcal{N} = 6$ supergravity, both with $G_4 = SO^*(12)$ [47]) and $\mathfrak{M}\left(J_3^{\mathbb{H}_s}\right)$ (non-supersymmetric theory, with $G_4 = SO(6,6)$ [52]), where $J_3^{\mathbb{H}}$ and $J_3^{\mathbb{H}_s}$ are rank-3 Euclidean Jordan algebras over the quaternions $\mathbb{H}$ and split quaternions $\mathbb{H}_s$, respectively.

In this case, the relevant $SO(12)$-representation is $R = \mathbf{32}$ or $R = \mathbf{32}'$, namely one of the two chiral spinor representations. The dimension $\dim S_{(a^p)}(\mathbf{32}^{(\prime)})^{SO(12)}$ for the partition $\lambda = a^p$, yielding the (real) dimension of the vector space of polynomial invariants of homogeneity degree pa in $p \dim R = 32p$ variables, is given as above:

$$\dim\left[S_{\lambda=a^p}\left(\mathbf{32}^{(\prime)}\right)\right]^{SO(12)} = \dim\left[S^{pa}\left(\mathbf{p}, \mathbf{32}^{(\prime)}\right)\right]^{SL_h(p,\mathbb{R})\times SO(12)} =: d.$$

(2.39)

By perusing the first few a's for the first few p's, one gets the following table:

$SO(12)$, $\mathbf{32}^{(\prime)}$	$a=$	0	1	2	3	4	5	6	7	8	9	10
$p=2$	$d=$	1	1	1	2	3	3	5	6	7	9	11
$p=3$	$d=$	1	0	0	0	5	0	0	0			
$p=4$	$d=$	1	1	2	5	17	42					
$p=5$	$d=$	1	0	0	0	42						
$p=6$	$d=$	1	1	3	14							
$p=7$	$d=$	1	0	0								
$p=8$	$d=$	1	1	4								

(2.40)

Considerations essentially analogous to the ones made for the cases of $G_4 = E_7$, $R = \mathbf{56}$ and $G_4 = Sp(6,\mathbb{R})$, $R = \mathbf{14}'$ hold in this case, as well.

2.3.4 $G_4 = SU(6)$, $R = \mathbf{20}$

This is related to the $D = 4$ theories with symmetric scalar manifold, based on the FTS's $\mathfrak{M}\left(J_3^{\mathbb{C}}\right)$ (magic $\mathcal{N} = 2$ Maxwell-Einstein theory over $J_3^{\mathbb{C}}$, with $G_4 = SU(3,3)$ [47]) and $\mathfrak{M}\left(J_3^{\mathbb{C}_s}\right)$ (non-supersymmetric theory, with $G_4 = SL(6,\mathbb{R})$ [52]), where $J_3^{\mathbb{C}}$ and $J_3^{\mathbb{C}_s}$ are rank-3 Euclidean Jordan algebras over the complex numbers $\mathbb{C}$ and split complex numbers $\mathbb{C}_s$, respectively[23].

In this case, the relevant $SU(6)$-representation is $R = \wedge^3 \mathbf{6} =: \mathbf{20}$, namely the rank-3 completely antisymmetric representation, built out from the fundamental representation $\mathbf{6}$. Due to the existence of the invariant ϵ-tensor in the $\mathbf{6}$ of $SU(6)$, the irrep. $\mathbf{20}$ is real. The dimension $\dim S_{(a^p)}(\mathbf{20})^{SU(6)}$ for the partition $\lambda = a^p$, yielding the (real) dimension of the vector space of polynomial invariants of homogeneity degree pa in $p \dim R = 20p$ variables, is given as above:

$$\dim\left[S_{\lambda=a^p}\left(\mathbf{20}\right)\right]^{SU(6)} = \dim\left[S^{pa}\left(\mathbf{p},\mathbf{20}\right)\right]^{SL_h(p,\mathbb{R})\times SU(6)} =: d. \tag{2.41}$$

By perusing the first few a's for the first few p's, one gets the following table:

$SU(6)$, $\mathbf{20}$	$a =$	0	1	2	3	4	5	6	7	8	9	10
$p = 2$	$d =$	1	1	1	2	3	3	5	6	7	9	11
$p = 3$	$d =$	1	0	1	0	5	0	9				
$p = 4$	$d =$	1	1	2	5	16	41					
$p = 5$	$d =$	1	0	1	0	37						
$p = 6$	$d =$	1	1	3	13							
$p = 7$	$d =$	1	0	2								
$p = 8$	$d =$	1	1	3								

$$\tag{2.42}$$

Considerations essentially analogous to the previous cases hold in this case, as well.

2.3.5 $G_4 = SL(2,\mathbb{R}) \times SL(2,\mathbb{R}) \times SL(2,\mathbb{R})$, $R = (\mathbf{2},\mathbf{2},\mathbf{2})$

We now consider the so-called $\mathcal{N} = 2$ *stu* model [33], whose U-duality group is $G_4 = SL(2,\mathbb{R}) \times SO(2,2) \cong SL(2,\mathbb{R})^3$, with the relevant BH flux representation being the tri-fundamental $R = (\mathbf{2},\mathbf{2},\mathbf{2})$.

This provides an example of group "of type E_7" [15] different from the ones treated above. Indeed, $SL(2,\mathbb{R})^3$ can still be characterized as a conformal symmetry, but of a *semi-simple*, rank-3 Jordan algebra, namely $J_3 = \mathbb{R} \oplus \mathbb{R} \oplus \mathbb{R}$, or equivalently as the automorphism group of the FTS $\mathfrak{M}(J_3)$ constructed over such an algebra:

$$SL(2,\mathbb{R})^3 = Conf\left(\mathbb{R} \oplus \mathbb{R} \oplus \mathbb{R}\right) = Aut\left(\mathfrak{M}\left(\mathbb{R} \oplus \mathbb{R} \oplus \mathbb{R}\right)\right). \tag{2.43}$$

Actually, by virtue of the isomorphism $\mathbb{R} \oplus \mathbb{R} \oplus \mathbb{R} \sim \mathbb{R} \oplus \Gamma_{1,1}$, this case can be regarded as the $(m,n) = (2,2)$ element of the infinite sequence of *semi-simple* rank-3 Jordan algebras $\mathbb{R} \oplus \Gamma_{m-1,n-1}$, where $\Gamma_{m-1,n-1}$ denotes the Clifford algebra of $O(m-1,n-1)$ [53]. This sequence can be related to $D = 4$ supergravity theories (displaying symmetric scalar manifolds) for m(or equivalently n)= 2 ($\mathcal{N} = 2$) or 6 ($\mathcal{N} = 4$). A complete basis of minimal degree (which turns out to be *finitely generating* [9]) of 2-centered BH invariant polynomials have been firstly determined in [32], and then further analyzed in [23] and [24].

The dimension $\dim S_{(a^p)}((\mathbf{2},\mathbf{2},\mathbf{2}))^{SL(2,\mathbb{R})^3}$ for the partition $\lambda = a^p$, yielding the (real) dimension of the vector space of polynomial invariants of homogeneity degree pa in $p \dim R = 8p$ variables, is given as above:

$$\dim\left[S_{\lambda=a^p}\left((\mathbf{2},\mathbf{2},\mathbf{2})\right)\right]^{SL(2,\mathbb{R})^3} = \dim\left[S^{pa}\left(\mathbf{p},\mathbf{2},\mathbf{2},\mathbf{2}\right)\right]^{SL_h(p,\mathbb{R})\times SL(2,\mathbb{R})^3} =: d. \tag{2.44}$$

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[23]Actually, another supergravity theory exists in which $R = \mathbf{20}$, namely $\mathcal{N} = 5$, $D = 4$ supergravity, with U-duality group $G_4 = SU(1,5)$. However, this theory cannot be uplifted to $D = 5$, and it is not related to a FTS, but rather to the *Jordan triple system* of 1×2 octonionic vectors $M_{1,2}(\mathbb{O})$ (see *e.g.* [47], and Refs. therein).

As done above, by perusing the first few a's for the first few p's, one gets the following table:

$SL(2,\mathbb{R})^3$, $(\mathbf{2},\mathbf{2},\mathbf{2})$	$a =$	0	1	2	3	4	5	6	7	8	9	10
$p = 2$	$d =$	1	1	3	4	7	9	14	17	24	29	38
$p = 3$	$d =$	1	0	0	0	10	0	1	0	57	0	28
$p = 4$	$d =$	1	1	4	8	15	27					
$p = 5$	$d =$	1	0	0	0	10						
$p = 6$	$d =$	1	1	3	4							
$p = 7$	$d =$	1	0	0								
$p = 8$	$d =$	1	1	1								

$$(2.45)$$

We observe that the $p = 2$ row of Table (2.45) differs from the one of Tables (2.31), (2.38), (2.40), (2.42), which instead all share the same row. This can be traced back to the *semi-simple* nature of the rank-3 Jordan algebra $\mathbb{R} \oplus \Gamma_{1,1}$ to which the *stu* model is be related, to be contrasted to the *simple* rank-3 Jordan algebras corresponding to the cases treated above.

Moreover, it should be stressed that Table (2.45) does not implement a peculiar symmetry of the *stu* model, namely the *triality symmetry*[24], corresponding to the invariance under the exchange of the three fundamentals $\mathbf{2}$'s in $R = (\mathbf{2},\mathbf{2},\mathbf{2})$, achieved by imposing an invariance under the symmetric group S_3 acting on the three $\mathbf{2}$'s in R.

The implementation of the *triality symmetry* will be explicitly worked out in Sec. 4 for the case of $p = 3$ and $a = 4$, namely for the vector space of 3-centered invariant polynomials of degree 12, which, from Table (2.45), has dimension 10; as yielded by the treatment of Sec. 4.3.4, the dimension of the vector space of 3-centered invariant polynomials of degree 12 which are *triality*- (namely, S_3-) symmetric, and thus relevant for black holes in the *stu* model, is 4.

Our analysis can be refined as follows : by looking directly for the $(SL_h(2,\mathbb{R}) \times G_4)$-invariants as above, we now consider the G_4-invariants in $S^k((\mathbb{R}^2) \otimes R)$. The formula (2.12) shows that these coincide with the G_4-invariants in $S_\lambda(R)$, tensored by the $SL_h(2,\mathbb{R})$-representation $S_\lambda(\mathbb{R}^2)$, where $\lambda \vdash k$ and $ht(\lambda) \leq 2$. By specifying this for the *stu* model, as done in all cases above, in Lie one types, for the partition $k = a + b$ with $a \geq b$, the following command (*cfr. e.g.* (2.29))

$$\text{plethysm}([a,b],[1,1,1],\text{A1A1A1})[1].\tag{2.46}$$

As mentioned, if $dX[0,0,0]$ occurs in the output, the coefficient d yields the dimension of the space of G_4-invariants in $S_{(a,b)}(R)$, otherwise there are no invariants in this representation.

In the 2-centered case ($p = 2$), an S_3-symmetric analysis of $SL(2,\mathbb{R})^3$- and $(SL_h(2,\mathbb{R}) \times SL(2,\mathbb{R})^3)$-invariant homogeneous polynomials for 2-centered BHs in the *stu* model has been performed in [32, 23, 24],whereas an S_4-symmetric treatment consistent in connection with the quantum entanglement of four qubits was given in [34].

Indeed, the relevant 2-centered representation for *stu* model is actually a *quadri-fundamental* : for $p = 2$ centers, one considers the invariants of the group $SL_h(2,\mathbb{R}) \times SL(2,\mathbb{R})^3$ in the representation $(\mathbf{2},\mathbf{2},\mathbf{2},\mathbf{2})$. Thus, one may promote the S_3-invariance (*triality*) to an invariance (*tetrality*) under the symmetric group S_4 acting on the four fundamentals $\mathbf{2}$'s in $(\mathbf{2},\mathbf{2},\mathbf{2},\mathbf{2})$. A complete, minimal degree basis for the ring of $(SL_h(2,\mathbb{R}) \times SL(2,\mathbb{R})^3)$- invariant homogeneous polynomials is given by $\mathcal{W}$, together with 2 quartic polynomials and with a sextic one, denoted by[25] $\mathbf{I}'_6$ [34].

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[24]The relevance of this symmetry to the theory of *Quantum Information*, and in particular to the classification of the quantum entanglement of three (and four) qubits has been recently studied, exploiting techniques and results from the supergravity side, also in the context of the so-called *BH/qubit correspondence* [37, 54, 55].

[25]Indeed, there is a slight difference in the definition of the $(SL_h(2,\mathbb{R}) \times G_4)$-invariant $\mathbf{I}_6$ for the models of $D = 4$ (super)gravity based on *simple* J_3's [22] with respect to the definition of $(SL_h(2,\mathbb{R}) \times G_4)$-invariant $\mathbf{I}'_6$ for the models of $D = 4$ (super)gravity based on the *semi-simple* sequence $J_{3,m,n} := \mathbb{R} \oplus \Gamma_{m-1,n-1}$ [32, 24]; this is discussed in Sec. 3 of [23].

When considering 2-centered BH physics, one must discriminate between the "horizontal" symmetry $SL_h(2, \mathbb{R})$ [32] and the U-duality symmetry $G_4 = SL(2, \mathbb{R})^3$, on which a *triality* must be implemented. Therefore, by down-grading S_4 (pertaining to four qubits in QIT) to S_3 (pertaining to 2-centered *stu* BHs), the consistent S_3-invariant $p = 2$ counting performed in [32, 23, 24] yields that an invariant polynomial of degree 8 is no more generated by the previous ones, and a *finitely generating* [9] complete basis for the ring of $(SL_h(2, \mathbb{R}) \times SL(2, \mathbb{R})^3)$- invariant homogeneous polynomials is given by four elements of degree 2, 4, 6 and 8 [32].

3   Geometric Interpretation

In this section we consider the invariants for $SL_h(p) \times G_4$ in $(\mathbb{R}^p) \otimes R =: (\mathbf{p}, R)$ in the case that[26]

$$p \leq r := \dim R. \tag{3.1}$$

Note that r is even whenever the symplectic invariant 2-form $\mathbb{C}_{MN}$ in $R_a^{\otimes 2}$ is non-degenerate (as we assume throughout the paper).

We start and recall some classical results (mainly referring to [35]), and then we discuss the associated geometrical interpretation in terms of Grassmannians.

The main result is the observation that the G_4-representation $S_{(a^p)}(R)$ which, as discussed in Sec. 2, produces all invariants in $S^{ap}((\mathbb{R}^p) \otimes R)$, can be identified with the representation of G_4 on the homogeneous polynomials of degree a in the *Plücker coordinates* of the p-planes in R. Each of these Plücker coordinates is an $SL_h(p)$-invariant homogeneous polynomial of degree p in the $p \dim R = pr$ coordinates on $(\mathbb{R}^p) \otimes R$. Thus, the G_4-invariant polynomials homogeneous of degree a in these Plücker coordinates provide exactly the $(SL_h(p) \times G_4)$-invariant homogeneous polynomials of degree ap which are the object of our investigation.

3.1   Grassmannians

3.1.1   Invariants of $SL_h(p) \times G_4$ in $(\mathbb{R}^p) \otimes R$

Any tensor t in $(\mathbb{R}^p) \otimes R$ can be written as a sum $t = \sum_{a=1}^{\min(r,p)} x_a \otimes y_a$, with $x_a \in \mathbb{R}^p$, $y_a \in R$. Let $f_1, \ldots, f_p$ be the standard basis of $\mathbb{R}^p$. Writing each $x_a = \sum_{i=1}^{p} x_{ai} f_i$, and using the bilinearity of $\otimes$, one finds that

$$t = \sum_{i=1}^{p} f_i \otimes r_i, \tag{3.2}$$

for certain uniquely determined elements $r_i \in R$.

Since any $(SL_h(p) \times G_4)$-invariant F is obviously an $(SL_h(p) \times \{I\})$-invariant, it is firstly convenient to study the invariants of $SL_h(p) \times \{I\}$. To this end, we only consider the action of $SL_h(p)$ on the first factor of $(\mathbb{R}^p) \otimes R$, so we are actually dealing with the direct sum of r copies of the

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[26]In the case $p > r$, one can easily show that there are no non-trivial invariants. This can be realized *e.g.* as follows.

One can write a tensor t as $t = \sum_{i=1}^{p} f_i \otimes r_i$ (see Eq. (3.2)). In the case $p > r$, it is however more convenient to choose a basis $e_1, \ldots, e_r$ of R, so that the same tensor can be rewritten as $t = \sum_{j=1}^{r} v_j \otimes e_j$, for (uniquely determined) vectors $v_j \in \mathbb{R}^p$.

For a generic t (to be precise, for t outside the closed subset of codimension > 1 of $\mathbb{R}^p \otimes R$ defined by the vanishing of $r \times r$ minors of the matrix with rows $v_1, \ldots, v_r$), the vectors $v_1, \ldots, v_r$ are *linearly independent*. Thus, there exists an element $A \in SL_h(p, \mathbb{R})$ such that $Av_i = f_i$, where $\{f_i\}$ is the standard basis of $\mathbb{R}^p$. Therefore, under the action of $SL_h(p, \mathbb{R}) \times \{I\}$ all t's in a dense open subset of $\mathbb{R}^p \otimes R$ can be transformed into the 'standard' tensor $t = \sum_{j=1}^{r} f_j \otimes e_j$.

Consequently, there is only one orbit (on this dense open set); as any $(SL_h(p, \mathbb{R}) \times G_4)$-invariant polynomial must be constant on this orbit, such a polynomial must be a constant, and thus trivial. Note that in the limit case $r = p$, it could actually be given by the determinant of the matrix $(v_1, \ldots, v_p)$ (this is actually the unique invariant in the case $r = p$), but if $r < p$ then the codimension of the complement of this open orbit is > 1, so a non-constant polynomial would be zero in one point and non-zero in another point of the open orbit, which yields a contradiction.

fundamental representation $\mathbb{R}^p =: \mathbf{p}$ of $SL_h(p)$. In the case $r \geq p$ (3.1), the ring of invariants in this case is well understood. Fixing a basis $e_1, \ldots, e_r$ of R, this ring is generated by the determinants of the $(p \times p)$-minors of the $r \times p$ matrix $T := T_t$ whose columns are the vectors $r_1, \ldots, r_p$ ([35], 11.1.2).

Note that all invariants F vanish on the tensors $t = \sum_{i=1}^p f_i \otimes r_i$ such that the rank of the matrix T_t is less than p, *i.e.* when the r_i do not span a p-dimensional subspace of R; such tensors t are called *unstable* (*i.e.*, not semi-stable) tensors for this action. The (geometric) quotient $((\mathbb{R}^p) \otimes R) // SL_h(p)$ is the image of the *quotient map* π given by generators of the ring of invariants F ([35], 11.1.2):

$$\pi : (\mathbb{R}^p) \otimes R \longrightarrow \wedge^p R, \qquad t = \sum_{i=1}^p f_i \otimes r_i \longmapsto r_1 \wedge r_2 \wedge \ldots \wedge r_p. \qquad (3.3)$$

Note that $\wedge^p R =: R_a^{\otimes p} = S_\lambda(R)$ (with partition $\lambda = 1^p$) has basis $e_I = e_{i_1} \wedge \ldots \wedge e_{i_p}$, with $i_1 < \ldots < i_p$, and therefore $\pi(t) = \sum t_I e_I$ (with I collectively denoting the indices $i_1 < \ldots < i_p$), where t_I is the determinant of the minor of T_t formed by the rows $i_1, \ldots, i_p$.

The image of the quotient map π (3.3) consists of the decomposable tensors in $\wedge^p R$. This map, when restricted to stable points, is the lift to linear spaces of the *Plücker map* $Gr(p, R) \to \mathbf{P}(\wedge^p R)$, where $Gr(p, R)$ denotes the *Grassmannian* of p-planes in R (see Sec. 3.1.3).

Let now F be an $(SL_h(p) \times G_4)$-invariant. Since it is trivially an $(SL_h(p) \times \{I\})$-invariant, from the above reasoning F is a polynomial in the determinants of $(p \times p)$-minors of T_t. Therefore, all such invariants can be determined with a two-step approach[27] :

1] first, one identifies the space of such polynomials as a representation of G_4;

2] then, one finds the G_4-invariants in that space.

Step **1** is actually well-known when one considers the space of such polynomials as a representation for the larger group $GL(R) =: GL(r)$ (namely, within (3.1)) : as a $GL(R)$-representation, the space of polynomials, homogeneous of degree a in the $(p \times p)$-minors of the $p \times r$ matrices, is $S_{a^p}(R)$ ([35], 11.1.2).

In order to find the $(SL_h(p) \times G_4)$-invariants in $(\mathbb{R}^p) \otimes R$, it then suffices to find the G_4-invariants in the representations $S_{a^p}(R)$ (step **2**). This conclusion was already reached in Sec. 2.2; however, the above discussion clarifies how a G_4-invariant in $S_{a^p}(R)$ produces a polynomial on $(\mathbb{R}^p) \otimes R$.

We are now going to reformulate this reasoning in a geometrical way.

3.1.2 From Tensors to Planes

In order to study p-centered BHs, for the case (3.1), one can use the Grassmannian $Gr(p, R)$ of p-planes in R as follows.

Using the notation of Sec. 3.1.1, any tensor t in $(\mathbb{R}^p) \otimes R$ can be written as $t = \sum_{i=1}^p f_i \otimes r_i$, for certain uniquely determined elements $r_i \in R$. It is here convenient to consider the dense open subset

$$(\mathbb{R}^p \otimes R)^0 := \left\{ \sum_{i=1}^p f_i \otimes r_i : \dim\langle r_1, \ldots, r_p \rangle = p \right\}, \qquad (3.4)$$

such that the p vectors $r_1, \ldots, r_p$ span a p-dimensional subspace of R (the upperscript "0" denotes the absence of unstable points). This yields a map $\mathbf{G}$ to $Gr(p, R)$ as follows:

$$\mathbf{G} : ((\mathbb{R}^p) \otimes R)^0 \longrightarrow Gr(p, R), \qquad t = \sum_{i=1}^p f_i \otimes r_i \longmapsto W_t := \langle r_1, \ldots, r_p \rangle. \qquad (3.5)$$

It is worth noting that the action of $SL_h(p)$ on $\mathbb{R}^p$ merely changes the basis of W_t, so the map $\mathbf{G}$ is $SL_h(p)$-invariant. It is obviously also $GL_h(p)$-invariant, so it is actually identifying more tensors

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[27]It is funny to note that this approach is actually the opposite of the method which has been exploited in supergravity (especially in the 2-centered case $p = 2$) : in that framework, the G_4-invariants are organized in irreps. of $SL_h(p)$, from which one picks out the trivial (singlet) $SL_h(p)$-representations (see *e.g.* [32, 22, 23, 24]).

than strictly necessary for our purposes. The map **G** (3.5), besides being injective, is obviously also surjective: indeed, given a p-plane $W \subset R$, one can choose a basis $r_1, \ldots, r_p$, and then $W = W_t$, where $t = \sum_{i=1}^{p} f_i \otimes r_i$. Thus, one gets the following bijection

$$((\mathbb{R}^p) \otimes R)^0 / GL_h(p) \longleftrightarrow Gr(p, R), \qquad t \longleftrightarrow W_t. \tag{3.6}$$

In particular, any G_4-invariant function on the Grassmannian $Gr(p, R)$ of p-planes in R will yield an $(SL_h(p) \times G)$-invariant function on $((\mathbb{R}^p) \otimes R)^0$, which will eventually extend[28] to the whole relevant irrep. $(\mathbb{R}^p) \otimes R$.

3.1.3 The Plücker Map

As $Gr(p, R)$ is (a real subset of) a projective variety, which is moreover a $p(r - p)$-dimensional homogeneous space:

$$Gr(p, r) \cong \frac{O(r)}{O(p) \otimes O(r - p)}, \tag{3.7}$$

one can proceed as follows. Recall that the *Plücker map* $\mathcal{P}$ is defined as the embedding

$$\mathcal{P} : Gr(p, R) \longrightarrow \mathbf{P}(\wedge^p R), \qquad W_t \longmapsto \wedge^p W_t. \tag{3.8}$$

In particular, the composition $\mathcal{P} \circ \mathbf{G}$ of this map with $\mathbf{G}$ (3.5) maps t to $r_1 \wedge \ldots \wedge r_p$. Fixing a basis $e_1, \ldots, e_r$ of R, one thus gets the basis $e_I = e_{i_1} \wedge \ldots \wedge e_{i_p}$, with $i_1 < \ldots < i_p$, of $\wedge^p R$ (*cfr.* below (3.3)). The *Plücker coordinates* of W_t are defined as the $(p \times p)$-minors of the $r \times p$ matrix $T := T_t$ with columns $r_1, \ldots, r_p$.

The action of the group $GL_h(R)$ can be represented on the space of global sections $\Gamma(Gr(p, R), L)$ on a line bundle L over $Gr(p, R)$. Working over the complex numbers and denoting by $Pic(X)$ the *Picard group* of the variety X, let us recall that $Pic(Gr(p, R))$ is generated by a (very ample) line bundle L, whose global sections are the Plücker coordinates themselves. In fact, $\Gamma(Gr(p, R), L) \cong \wedge^p R$, (actually the dual representation thereof, since the coordinates are linear maps on $\wedge^p R$). The action of $GL_h(R)$ on R then induces an action on the Grassmannian $Gr(p, R)$ and thus on the spaces of global sections $\Gamma(Gr(p, R), L)$. By recalling that $\wedge^p R = S_\lambda(R)$ with partition $\lambda = 1^p$ (*cfr.* below (2.6)), Bott's theorem (see *e.g.* [46]) gives, as $GL_h(R)$-representations:

$$\Gamma(Gr(p, R), L^{\otimes a}) \cong S_{a\lambda}(R), \qquad a\lambda := \underbrace{(a, \ldots, a)}_{p} =: a^p. \tag{3.9}$$

Furthermore, any global section of $L^{\otimes a}$ is a linear combination of products of a sections of L (and therefore the map $S^a \Gamma(L) \to \Gamma(L^{\otimes a})$ is surjective); in terms of representations, this simply amounts to the statement that $S_{a\lambda}$ is a summand of $S^{ap}(R)$. Thus, any section of $L^{\otimes a}$ is a homogeneous polynomial in the Plücker coordinates of degree a.

Given a G_4-invariant $F \in S_{a\lambda}(R) \cong \Gamma(Gr(p, R), L^{\otimes a})$, it corresponds to a degree a homogeneous polynomial in the Plücker coordinates, defined by the map (recall (3.5) and (3.6)):

$$F : Gr(p, R) \longrightarrow \mathbb{R}, \tag{3.10}$$

Thus, the composition

$$F \circ \mathbf{G} : ((\mathbb{R}^p) \otimes R)^0 \longrightarrow \wedge^p R \longrightarrow \mathbb{R}, \tag{3.11}$$

yields a $(SL_h(p) \times G_4)$-invariant which extends to the whole $(\mathbb{R}^p) \otimes R$. This provides a geometrical explanation of the treatment of Sec. 2, and in particular of the fact that the $S_\lambda(R)$ with $\lambda = a^p$

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[28] In the present investigation, as resulting from Sec. 2, we consider *homogeneous polynomial* invariants; in such a case, the extension from $((\mathbb{R}^p) \otimes R)^0$ to the whole $(\mathbb{R}^p) \otimes R$ is immediate.

contribute to - *and actually are the unique responsible for* - the $(SL_h(p) \times G_4)$-invariant homogeneous polynomials in $(\mathbb{R}^p) \otimes R$.

To summarize, in order to find $(SL_h(p) \otimes G_4)$-invariant homogeneous polynomials F in the representation $(\mathbb{R}^p) \otimes R$, one needs to find invariant polynomials $\hat{F}$ for the induced action of G_4 on $\wedge^p R$:

$$F(t) = \hat{F}(\dots, p_{i_1 \dots i_p}(t), \dots), \qquad (3.12)$$

where $p_{i_1 \dots i_p}(t) = p_{[i_1 \dots i_p]}(t)$.

In particular, if an invariant F is a homogeneous polynomial of degree k in the coefficients c_{ij} of $t = \sum c_{ij} f_i \otimes e_j$, then, as each Plücker coordinate is homogeneous of degree p in the c_{ij}, $\hat{F}$ is homogeneous of degree k/p in the Plücker coordinates. Thus, k *must be a multiple of* p. This matches the statement made below (2.15), and it is not surprising, as $SL(p, \mathbb{C})$ contains the diagonal matrices ωI where $\omega = e^{2\pi i/p}$ and these act by multiplication by ω^d on polynomials F of degree k; so, if F is $SL_h(p)$-invariant, k must indeed be a multiple of p. Moreover, these invariants $\hat{F}$ should be non-zero when restricted to the (semi-)stable decomposable tensors.

4   3-centered *stu* Black Holes

We will now apply the method discussed in Secs. 2 and 3 to compute the invariants pertaining to 3-centered ($p = 3$) BHs in the $\mathcal{N} = 2$, $D = 4$ *stu* model [33]. As discussed in Sec. 2.3.5, in this case the U-duality group is $G_4 = SL(2, \mathbb{R}) \times SO(2, 2) \cong SL(2, \mathbb{R})^3$, with the relevant BH representation being the tri-fundamental $R = (\mathbf{2}, \mathbf{2}, \mathbf{2})$. Moreover, the K-tensor (namely, the unique rank-4 symmetric invariant in $(\mathbf{2}, \mathbf{2}, \mathbf{2})_s^{\otimes 4}$; see Sec. 1) is given by the *Cayley's hyperdeterminant* on R [36, 37].

In Table (2.45), we have computed the dimension of the spaces of invariants for $p = 3$ up to degree 30. In particular, the lowest degree non-trivial $\left(SL_h(3, \mathbb{R}) \times SL(2, \mathbb{R})^3 \right)$-invariant homogeneous polynomials in the $\mathbb{R}^3 \otimes (\mathbf{2}, \mathbf{2}, \mathbf{2}) =: (\mathbf{3}, \mathbf{2}, \mathbf{2}, \mathbf{2})$ have degree 12, and they span a 10-dimensional space.

From the treatment of Secs. 2 and 3, as well as from Table (2.45), such 3-centered invariant polynomials lie in $S_{4^3}((\mathbf{2}, \mathbf{2}, \mathbf{2}))$. In the present Section, we will determine a basis for their 10-dimensional space. Then, in Subsubsec. 4.3.4 we will implement invariance (*triality*) under the S_3 symmetric group acting on the three $\mathbf{2}$'s in R, obtaining a basis of the resulting 4-dimensional vector space of $\left(S_3 \times SL_h(3, \mathbb{R}) \times SL(2, \mathbb{R})^3 \right)$-invariant homogeneous polynomials of degree 12 in the $(\mathbf{3}, \mathbf{2}, \mathbf{2}, \mathbf{2})$, thus pertaining to the description of 3-centered BHs in the *stu* model.

4.1   Invariant from Cayley's Hyperdeterminant : $S^4(S_{1^3}((\mathbf{2}, \mathbf{2}, \mathbf{2})))$

A first invariant can be constructed as follows.

Let us recall that the BH flux irrep. $R = (\mathbf{2}, \mathbf{2}, \mathbf{2})$ is endowed with an invariant alternating form $\mathbb{C}$, *i.e.* the symplectic 8×8 metric $\mathbb{C}_{MN} := (\exists!) \mathbf{1} \in (\mathbf{2}, \mathbf{2}, \mathbf{2})_a^{\otimes 2}$. Within the notation of Sec. 3.1, the restriction of $\mathbb{C}_{MN}$ to the 3-dimensional subspace $W_t \subset (\mathbf{2}, \mathbf{2}, \mathbf{2})$ generated by 3 given charge vectors $Q_i =: r_i \in (\mathbf{2}, \mathbf{2}, \mathbf{2})$ (we here denote the "horizontal" index as $i = 1, 2, 3 = p$) is given by the 3×3 alternating matrix

$$\mathbb{C}_t := \mathbb{C}|_{W_t \otimes W_t} = \begin{pmatrix} 0 & (r_1, r_2) & (r_1, r_3) \\ (r_2, r_1) & 0 & (r_2, r_3) \\ (r_3, r_1) & (r_3, r_2) & 0 \end{pmatrix}, \qquad W_t := \langle r_1, r_2, r_3 \rangle \subset (\mathbf{2}, \mathbf{2}, \mathbf{2}), \qquad (4.1)$$

where (*cfr.* (2.17); $M = 1, ..., 8 = \dim(\mathbf{2}, \mathbf{2}, \mathbf{2})$)

$$(\mathbb{C}_t)_{ij} = (r_i, r_j) := \mathbb{C}_{MN} r_i^M r_j^N =: \mathcal{W}_{ij} = -\mathcal{W}_{ji} \qquad (4.2)$$

is the $SL(2, \mathbb{R})^3$-invariant symplectic product of r_i and r_j. It is immediate to realize that $\mathcal{W}_{ij}$ ($i, j = 1, 2, 3$) belongs to the $\mathbf{3}' = \wedge^2 \mathbf{3}$ of $SL_h(3, \mathbb{R})$ (cfr. end of Sec. 2.2.1, as well as the end of Sec. 3 of [22]); indeed, by using the Ricci-Levi-Civita invariant symbol ϵ^{ijk} of $SL_h(3, \mathbb{R})$, one can define

$$\mathcal{W}^i := \frac{1}{2}\epsilon^{ijk}\mathbb{C}_{MN}r_j^M r_k^N = \frac{1}{2}\epsilon^{ijk}\mathcal{W}_{jk} \in \left(\mathbf{3}', \mathbf{1}, \mathbf{1}, \mathbf{1}\right) \text{ of } SL_h(3, \mathbb{R}) \times SL(2, \mathbb{R})^3. \tag{4.3}$$

The vector

$$v_t := (r_2, r_3)r_1 + (r_3, r_1)r_2 + (r_1, r_2)r_3 = \frac{1}{2}\epsilon^{ijk}\mathcal{W}_{jk}r_i = \frac{1}{2}\epsilon^{ijk}\mathcal{W}_{[jk}r_{i]} \in W_t \tag{4.4}$$

spans the kernel of $\mathbb{C}_t$ (4.1), and it can be considered as a multilinear alternating map

$$v_t : (\mathbf{2}, \mathbf{2}, \mathbf{2})^{\otimes 3} \longrightarrow (\mathbf{2}, \mathbf{2}, \mathbf{2}), \qquad (r_1, r_2, r_3) \longmapsto (r_2, r_3)r_1 + (r_3, r_1)r_2 + (r_1, r_2)r_3. \tag{4.5}$$

In order to see this, it suffices to check that it is alternating for the permutations (12) and (23), which is easily done. Thus, the map v_t (4.5) induces a linear map $\wedge^3(\mathbf{2}, \mathbf{2}, \mathbf{2}) \to (\mathbf{2}, \mathbf{2}, \mathbf{2})$; by virtue of the treatment of Sec. 3, this proves that v_t is a linear combination of the r_i with coefficients which are linear forms in the Plücker coordinates of t. From the treatment of Sec. 3, these Plücker coordinates are homogeneous of degree $p = 3$ in the coordinates c_{ij} of t, and they are invariant under the action of $SL_h(3, \mathbb{R})$, hence

$$v_t = v_{(A,I)t}, \quad \forall A \in SL_h(3, \mathbb{R}), \tag{4.6}$$

implying that

$$v_t \in (\mathbf{1}, W_t) \subset (\mathbf{1}, \mathbf{2}, \mathbf{2}, \mathbf{2}). \tag{4.7}$$

As the symplectic 2-form $\mathbb{C}$ is $SL(2, \mathbb{R})^3$-invariant, by recalling definition (4.4) one obtains the following formula for the action of $B \in SL(2, \mathbb{R})^3$ on v_t itself:

$$\begin{aligned} Bv_t &= (r_2, r_3)Br_1 + (r_3, r_1)Br_2 + (r_1, r_2)Br_3 \\ &= (Br_2, Br_3)Br_1 + (Br_3, Br_1)Br_2 + (Br_1, Br_2)Br_3 \\ &= v_{(I,B)t}. \end{aligned} \tag{4.8}$$

By virtue of (4.6), since

$$v_{(A,B)t} = v_{(A,I)(I,B)t} = v_{(I,B)t} = Bv_t, \tag{4.9}$$

any $SL(2, \mathbb{R})^3$-invariant polynomial F of degree g on the tri-fundamental representation $R = (\mathbf{2}, \mathbf{2}, \mathbf{2})$ produces an $\left(SL_h(3, \mathbb{R}) \times SL(2, \mathbb{R})^3\right)$-invariant polynomial F_0 homogeneous of degree $3g$ on $(\mathbf{3}, \mathbf{2}, \mathbf{2}, \mathbf{2})$, defined as follows:

$$F_0(t) := F(v_t). \tag{4.10}$$

A natural choice is $F = \mathcal{I}_4$, where $\mathcal{I}_4$ is the *Cayley's hyperdeterminant* [36] on $(\mathbf{2}, \mathbf{2}, \mathbf{2})$ (determined by the K-tensor of $(\mathbf{2}, \mathbf{2}, \mathbf{2})$ [36, 37]); this is an homogeneous polynomial of degree 4, and it is the *unique* algebraically independent $SL(2, \mathbb{R})^3$-invariant polynomial on the $(\mathbf{2}, \mathbf{2}, \mathbf{2})$ itself. Therefore, the choice $F = \mathcal{I}_4$ yields an $\left(SL_h(3, \mathbb{R}) \times SL(2, \mathbb{R})^3\right)$-invariant polynomial F_0 homogeneous of degree $3 \cdot 4 = 12$ for 3-centered BHs in the *stu* model:

$$F_0(t) := \mathcal{I}_4(v_t). \tag{4.11}$$

The construction performed above can be clarified in terms of representation theory as follows.

From the treatment of Secs. 2 and 3 (in particular, recalling (3.12)), the $(SL_h(3, \mathbb{R}) \otimes G_4)$-invariants homogeneous polynomials F on $(\mathbb{R}^3) \otimes R =: (\mathbf{3}, R)$ are given by invariants $\hat{F}$ for the induced action of G_4 on $\wedge^3 R =: R_a^{\otimes 3} = S_\lambda(R)$ (with partition $\lambda := 1^3$; see below (2.6)):

$$F(t) = \hat{F}(\ldots, p_{i_1 i_2 i_3}(t), \ldots), \tag{4.12}$$

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(where $p_{i_1 i_2 i_3}(t) = p_{[i_1 i_2 i_3]}(t)$) which should be non-zero when restricted to the (semi-)stable decomposable tensors.

In general, the representations of G_4 on $\wedge^3 R$ may be reducible. Indeed, for the *stu* model we have

$$S_{1^3}((\mathbf{2,2,2})) := \wedge^3 (\mathbf{2,2,2}) \equiv (\mathbf{2,2,2})_a^{\otimes 3} \cong (\mathbf{2,2,2}) \oplus (\mathbf{4,2,2}) \oplus (\mathbf{2,4,2}) \oplus (\mathbf{2,2,4}), \qquad (4.13)$$

where $\mathbf{4}$ denotes the spin $s = 3/2$ irrep. of $SL(2,\mathbb{R})$.

The appearance of $(\mathbf{2,2,2})$ in the r.h.s. of (4.13), and in general the fact that $R \in R_a^{\otimes 3}$, can be simply related to the existence of the G_4-equivariant map

$$R \longrightarrow \wedge^3 R, \qquad r \longmapsto \mathbb{C}^* \wedge r \qquad (4.14)$$

where $\mathbb{C} \in \wedge^2 R^*$ corresponds to $\mathbb{C}^* \in \wedge^2 R$ under the duality given by the non-degenerate symplectic form $\mathbb{C} \equiv \mathbb{C}_{MN} = \mathbb{C}_{[MN]}$ on R (symplectic structure of - generalized - electric-magnetic duality in $D = 4$). This implies that any G_4-invariant on R trivially produces a G_4-invariant on $\wedge^3 R$.

Let us call Ψ_t the generalization (for a generic case) of the map v_t (4.4)-(4.5) constructed above:

$$\Psi_t : \wedge^3 R \longrightarrow R, \quad r_1 \wedge r_2 \wedge r_3 \longmapsto (r_2, r_3) r_1 + (r_3, r_1) r_2 + (r_1, r_2) r_3 \qquad (4.15)$$

which then satisfies (*cfr.* (4.8))

$$\Psi_t(B(r_1 \wedge r_2 \wedge r_3)) := \Psi_t((Br_1) \wedge (Br_2) \wedge (Br_3)) = B\Psi_t(r_1 \wedge r_2 \wedge r_3), \ \forall B \in G_4, \qquad (4.16)$$

since $(Br_i, Br_j) = (r_i, r_j)$. Thus the map Ψ_t (4.15) is, up to scalar multiplication, the unique G_4-equivariant projection of $\wedge^3 R$ onto R.

Thus, coming back to the *stu* model, it follows that, up to a real scalar, the map $\pi : (\mathbf{3,2,2,2}) \to \wedge^3 (\mathbf{2,2,2})$ (*cfr.* (3.3) for $p = 3$) is given by

$$\pi(t) = v_t + w_t, \qquad v_t := \Psi_t(W_t) \in (\mathbf{2,2,2}), \quad w_t \in (\mathbf{4,2,2}) \oplus (\mathbf{2,4,2}) \oplus (\mathbf{2,2,4}). \qquad (4.17)$$

This leads to the invariant F_0 (4.11), which is thus given by the image of $S^4(S_{1^3}(\mathbf{2,2,2}))$ in $S_{4,4,4}((\mathbf{2,2,2}))$.

From the treatment above, it clearly follows that the degree-12 homogeneous $(SL_h(3,\mathbb{R}) \times G_4)$-invariant polynomial F_0 (4.11) can be consistently defined for all groups G_4 "of type E_7", and in particular *at least* for the class relevant to $D = 4$ supergravity theories with symmetric scalar manifolds, listed in Table 1.

4.2 Other Invariants from $S^2(S_{2^3}((\mathbf{2,2,2})))$

As a natural next step, one can try to determine other $SL(2,\mathbb{R})^3$-invariants of degree 12 from quadratic invariants in $S_{2^3}((\mathbf{2,2,2}))$.

Using LiE, one can decompose $S_{2^3}((\mathbf{2,2,2}))$ into irreducible $SL(2,\mathbb{R})^3$-representations:

$$S_{2^3}((\mathbf{2,2,2})) \cong (\mathbf{3,1,1})^{\oplus 3} \oplus (\mathbf{1,3,1})^{\oplus 3} \oplus (\mathbf{1,1,3})^{\oplus 3} \oplus \ldots, \qquad (4.18)$$

where the dots denote other 25 terms, which are not relevant for our purposes. $\mathbf{3}$ denotes the adjoint (spin $s = 1$) irrep. of $SL(2,\mathbb{R})$, which has a unique quadratic invariant (the $SL(2,\mathbb{R}) \sim SO(2,1)$ Cartan-Killing invariant metric $\eta = diag(1, 1 - 1)$); as a consequence, since $\mathbf{1}$ denotes the singlet, there is a unique quadratic invariant induced onto the $(\mathbf{3,1,1})$, $(\mathbf{1,3,1})$ and $(\mathbf{1,1,3})$ of $SL(2,\mathbb{R})^3$. Thus, from the representations in the r.h.s. of (4.18), one obtains $3 \cdot 3 = 9$ quadratic $SL(2,\mathbb{R})^3$-invariant structures:

$$\begin{aligned} &\exists! \, (\mathbf{1,1,1}) \in (\mathbf{3,1,1}) \otimes_s (\mathbf{3,1,1}) \quad (\text{3 times}); \\ &\exists! \, (\mathbf{1,1,1}) \in (\mathbf{1,3,1}) \otimes_s (\mathbf{1,3,1}) \quad (\text{3 times}); \\ &\exists! \, (\mathbf{1,1,1}) \in (\mathbf{1,1,3}) \otimes_s (\mathbf{1,1,3}) \quad (\text{3 times}). \end{aligned} \qquad (4.19)$$

One can check that these 9 invariants, together with F_0 (4.11), yield 10 linearly independent invariants in $S_{4^3}((\mathbf{2,2,2}))$. Thus, as announced, they do provide a complete basis for the 10-dimensional space of $\left(SL_h(3,\mathbb{R}) \times SL(2,\mathbb{R})^3\right)$-invariant homogeneous polynomials of degree 12 in the $(\mathbf{3,2,2,2})$, as resulting from Table (2.45).

4.3 Explicit Construction

Let f_1, f_2, f_3 and $e_1, \ldots, e_8$ be the standard basis of $\mathbb{R}^3 =: \mathbf{3}$ of $SL_h(3, \mathbb{R})$, and of $(\mathbf{2}, \mathbf{2}, \mathbf{2})$ of $SL(2, \mathbb{R})^3$, respectively. Thus, any tensor $t \in (\mathbf{3}, \mathbf{2}, \mathbf{2}, \mathbf{2})$ of $SL_h(3, \mathbb{R}) \times SL(2, \mathbb{R})^{\otimes 3}$ can be written as[29] (using the notation of Sec. (3.1.1), and in particular denoting the "horizontal" index by $i = 1, 2, 3$)

$$t = \sum_{i=1,2,3, \ j=1,\ldots,8} c_{ij} f_i \otimes e_j = \sum_{i=1}^{3} f_i \otimes r_i, \tag{4.20}$$

for certain uniquely determined elements $r_i \in (\mathbf{2}, \mathbf{2}, \mathbf{2})$ of $SL(2, \mathbb{R})^3$.

As discussed in Sec. 3, the *Plücker coordinates* $p_{i_1 i_2 i_3}(t)$ of the tensor t are the determinants of the 3×3 matrices formed by the the rows i_1, i_2, i_3 of the 8×3 matrix which has columns r_1, r_2, r_3:

$$p_{i_1 i_2 i_3}(t) = \det \begin{pmatrix} c_{1i_1} & c_{2i_1} & c_{3i_1} \\ c_{1i_2} & c_{2i_2} & c_{3i_2} \\ c_{1i_3} & c_{2i_3} & c_{3i_3} \end{pmatrix}. \tag{4.21}$$

This is the formula defining $p_{i_1 i_2 i_3} = p_{[i_1 i_2 i_3]}$, and their number is indeed $\binom{8}{3} = 56$.

In the *stu* model $G_4 = SL(2, \mathbb{R})^3$, with Lie algebra $\mathfrak{G}_4 = \mathfrak{sl}(2, \mathbb{R})^{\oplus 3}$. Denoting by X_a (raising operator), Y_a (lowering operator), and $H_a := [X_a, Y_a]$ the standard generators of the a-th ($a = 1, 2, 3$) copy of the Lie algebra $\mathfrak{sl}(2, \mathbb{R})$, the action of $\mathfrak{sl}(2, \mathbb{R})^{\oplus 3}$ on a vector $(c_{i1}, \ldots, c_{i8}) \in (\mathbf{2}, \mathbf{2}, \mathbf{2})$ can be realized through the identification ($i = 1, 2, 3$)[30]

$$\begin{aligned} (c_{11}, \ldots, c_{18}) &= (x_{000}, x_{001}, x_{010}, x_{011}, x_{100}, x_{101}, x_{110}, x_{111}); \\ (c_{21}, \ldots, c_{28}) &= (y_{000}, y_{001}, y_{010}, y_{011}, y_{100}, y_{101}, y_{110}, y_{111}); \\ (c_{31}, \ldots, c_{38}) &= (z_{000}, z_{001}, z_{010}, z_{011}, z_{100}, z_{101}, z_{110}, z_{111}), \end{aligned} \tag{4.22}$$

where the fundamental (spin $s = 1/2$) irrep. $\mathbf{2}$ of $SL(2, \mathbb{R})$ is spanned by the indices $\mathbf{a} = 0, 1$. For example, the first copy of $\mathfrak{sl}(2, \mathbb{R})$ in $\mathfrak{sl}(2, \mathbb{R})^{\oplus 3}$ acts on the $x_{\mathbf{abc}}$ (equivalently denoting $x_{\mathbf{abc}}$ or $y_{\mathbf{abc}}$ or $z_{\mathbf{abc}}$) as follows:

$$X_1 x_{\mathbf{abc}} = \begin{cases} 0 & \text{if } \mathbf{a} = 0; \\ x_{0\mathbf{bc}} & \text{if } \mathbf{a} = 1; \end{cases} \quad Y_1 x_{\mathbf{abc}} = \begin{cases} x_{1\mathbf{bc}} & \text{if } \mathbf{a} = 0; \\ 0 & \text{if } \mathbf{a} = 1; \end{cases} \quad H_1 x_{\mathbf{abc}} = \begin{cases} x_{\mathbf{abc}} & \text{if } \mathbf{a} = 0; \\ -x_{\mathbf{abc}} & \text{if } \mathbf{a} = 1, \end{cases} \tag{4.23}$$

and similarly for the other two copies.

Then, one can compute the action of $\mathfrak{sl}(2, \mathbb{R})^{\oplus 3}$ on the *Plücker coordinates* (4.21), exploiting the fact that elements of $\mathfrak{sl}(2, \mathbb{R})^{\oplus 3}$ act as *derivations* on the $p_{i_1 i_2 i_3}$'s themselves. For example, by using the identification (4.22), the action of X_1 of the first copy of $\mathfrak{sl}(2, \mathbb{R})$ in $\mathfrak{sl}(2, \mathbb{R})^{\oplus 3}$ on p_{167} (4.21) reads

$$X_1 p_{167} = X_1 \det \begin{pmatrix} x_{000} & y_{000} & z_{000} \\ x_{101} & y_{101} & z_{101} \\ x_{110} & y_{110} & z_{110} \end{pmatrix} = \det \begin{pmatrix} x_{000} & y_{000} & z_{000} \\ x_{001} & y_{001} & z_{001} \\ x_{110} & y_{110} & z_{110} \end{pmatrix} + \det \begin{pmatrix} x_{000} & y_{000} & z_{000} \\ x_{101} & y_{101} & z_{101} \\ x_{010} & y_{010} & z_{010} \end{pmatrix}; \tag{4.24}$$

therefore, by using the antisymmetry of the *Plücker coordinates* (4.21), one finds that $X_1 p_{167} = p_{127} - p_{136}$. In this way, one can compute the action of each of the 9 generators $\{X_1, Y_1, H_1, X_2, Y_2, H_2, X_3, Y_3, H_3\}$ of $\mathfrak{sl}(2, \mathbb{R})^{\oplus 3}$ on the representation $\wedge^3(\mathbf{2}, \mathbf{2}, \mathbf{2})$ (realized in terms of *Plücker coordinates* (4.21); also *cfr.* (3.8)) of $SL(2, \mathbb{R})^3$. Such an action then extends to an action by *derivations* on polynomials in the $p_{i_1 i_2 i_3}$'s themselves.

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[29]In 3-centered BH physics, the c_{ij} ($i = 1, 2, 3, j = 1, \ldots, 8$) spanning the $(\mathbf{3}, \mathbf{2}, \mathbf{2}, \mathbf{2})$ of $SL_h(3, \mathbb{R}) \times SL(2, \mathbb{R})^3$ would usually be denoted as Q_a^M, with $a = 1, 2, 3$ being the "horizontal" $SL_h(3, \mathbb{R})$-index, and $M = 1, \ldots, 8$ denoting the U-duality $SL(2, \mathbb{R})^3$-index.

[30]In physics literature, the basis $\{x_{\mathbf{abc}}\}_{\mathbf{a}, \mathbf{b}, \mathbf{c} = 0, 1}$ is named *qubit basis*, because it naturally occurs in the quantum entanglement of three *qubits* in *Quantum Information Theory*. For relation to other symplectic frames in the *stu* model as well as recent developments related to the *BH/qubit correspondence*, see *e.g.* [33, 55, 56, 57] and [54], respectively.

4.3.1 The Representation $V(a_1, a_2, a_3)$

Let us now consider the realization of the representation $V(a_1, a_2, a_3)$ of $G_4 = SL(2, \mathbb{R})^3$ on the space of homogeneous polynomials; here, we use the standard notation in which $V(a_1, a_2, a_3) := (\mathbf{a_1+1}, \mathbf{a_2+1}, \mathbf{a_3+1})$, and thus it has (real) dimension $(a_1 + 1)(a_2 + 1)(a_3 + 1)$ (namely, (a_1, a_2, a_3) denote the weights of the vector space V as $SL(2, \mathbb{R})^3$-representation).

The *highest weight* vector $v \in V(a_1, a_2, a_3)$ satisfies

$$\begin{cases} H_i v = a_i v; \\ X_i v = 0; \end{cases} \quad i = 1, 2, 3. \tag{4.25}$$

Thus, $V(a_1, a_2, a_3)$ can be realized as the vector space spanned by certain combinations of powers of lowering operators X_i's on its highest weight vector v itself:

$$V(a_1, a_2, a_3) = \langle Y_1^k Y_2^l Y_3^m v \; : \; 0 \leq k \leq a_1, \; 0 \leq l \leq a_2, \; 0 \leq m \leq a_3 \rangle. \tag{4.26}$$

By virtue of (4.25), the vector $Y_1^k Y_2^l Y_3^m v \in V(a_1, a_2, a_3)$ is again an eigenvector of all three H_i's with weight $(a_1 - 2k, a_2 - 2l, a_3 - 2m)$.

We are now going to exploit this general description in order to explicitly construct the 10 $\left(SL_h(3, \mathbb{R}) \times SL(2, \mathbb{R})^3 \right)$-invariant homogeneous polynomials of degree 12 in the $(\mathbf{3}, \mathbf{2}, \mathbf{2}, \mathbf{2})$ considered in Secs. 4.1 and 4.2, which constitute a complete basis for the corresponding 10-dimensional vector space resulting from Table (2.45).

4.3.2 The $(\mathbf{2}, \mathbf{2}, \mathbf{2})$ in $S_{1^3}((\mathbf{2}, \mathbf{2}, \mathbf{2}))$

Below (4.13), we observed that there is a (unique) irreducible tri-fundamental $SL(2, \mathbb{R})^3$-representation $V(1, 1, 1) =: (\mathbf{2}, \mathbf{2}, \mathbf{2})$ in $S_{1^3}((\mathbf{2}, \mathbf{2}, \mathbf{2})) = \wedge^3(\mathbf{2}, \mathbf{2}, \mathbf{2}) =: (\mathbf{2}, \mathbf{2}, \mathbf{2})_a^{\otimes 3}$. In order to characterize it, we here determine its highest weight vector.

Besides $(\mathbf{2}, \mathbf{2}, \mathbf{2})$, also each of the other 3 irreducible summands of $S_{1^3}((\mathbf{2}, \mathbf{2}, \mathbf{2}))$ in the r.h.s. of (4.13) has a vector with weight $(1, 1, 1)$, therefore the weight space $S_{1^3}((\mathbf{2}, \mathbf{2}, \mathbf{2}))_{(1,1,1)}$ is four-dimensional:

$$\begin{aligned} S_{1^3}((\mathbf{2}, \mathbf{2}, \mathbf{2}))_{(1,1,1)} \quad : \quad &= \{ v \in S_{1^3}((\mathbf{2}, \mathbf{2}, \mathbf{2})) : H_i v = v, \quad i = 1, 2, 3 \} \\ &= \langle p_{145}, p_{136}, p_{235}, p_{127} \rangle, \end{aligned} \tag{4.27}$$

as one can check within the conventions adopted above. The unique (up to a scalar multiple) highest weight vector in this space is

$$v := p_{145} - p_{136} - p_{127}, \qquad \text{so} \quad \langle v \rangle = \cap_{i=1}^3 \ker(X_i) \cap S_{1^3}((\mathbf{2}, \mathbf{2}, \mathbf{2}))_{(1,1,1)}. \tag{4.28}$$

Thus, an isomorphism between $(\mathbf{2}, \mathbf{2}, \mathbf{2}) \subset S_{1^3}((\mathbf{2}, \mathbf{2}, \mathbf{2}))$ and $(\mathbf{2}, \mathbf{2}, \mathbf{2})$ itself can be obtained, by setting

$$x_{klm} := Y_1^k Y_2^l Y_3^m v, \qquad k, l, m \in \{0, 1\}, \tag{4.29}$$

where v is defined in (4.28).

The usual expression of the $SL(2, \mathbb{R})^3$-invariant *Cayley's hyperdeterminant* $\mathcal{I}_4$ [36] in the trifundamental $(\mathbf{2}, \mathbf{2}, \mathbf{2})$ as a quartic homogeneous polynomial in the x_{ijk}'s [37] (in *qubit basis*; *cfr.* footnote 30) produces a degree-4 polynomial in the *Plücker coordinates* $p_{ijk}(t)$ (4.21). As a polynomial in the c_{ij} (*cfr. e.g.* the first line of (4.22)), such a polynomial is then $\left(SL_h(3, \mathbb{R}) \times SL(2, \mathbb{R})^3 \right)$-invariant homogeneous of degree 12 in the $(\mathbf{3}, \mathbf{2}, \mathbf{2}, \mathbf{2})$; indeed, as expected, one can check that it coincides with the invariant $F_0(t)$ (4.11).

4.3.3 The $(\mathbf{1},\mathbf{1},\mathbf{3})^{\oplus 3}$ in $S_{2^3}\left((\mathbf{2},\mathbf{2},\mathbf{2})\right)$

The $SL\left(2,\mathbb{R}\right)^3$-representation $S_{2^3}\left((\mathbf{2},\mathbf{2},\mathbf{2})\right)$ is a sub-representation of $S^2(S_{1^3}\left((\mathbf{2},\mathbf{2},\mathbf{2})\right)) =: \left((\mathbf{2},\mathbf{2},\mathbf{2})_a^{\otimes 3}\right)_s^{\otimes 2}$, which is the space of homogenous polynomials of degree 2 in the *Plücker coordinates* $p_{ijk}(t)$; in fact, by substituting the cubic polynomials (4.21) in the c_{ij} for these p_{ijk}, one gets a vector space of degree-6 homogeneous polynomials in the c_{ij}'s, which is nothing but $S_{2^3}\left((\mathbf{2},\mathbf{2},\mathbf{2})\right)$.

Using this fact, one can first determine the weight space

$$
\begin{aligned}
S^2(S_{1^3}\left((\mathbf{2},\mathbf{2},\mathbf{2})\right))_{(0,0,2)} \quad &: \quad = \{v \in S^2(S_{1^3}\left((\mathbf{2},\mathbf{2},\mathbf{2})\right)) : H_i v = 0, \quad i=1,2, \quad H_3 v = 2v\} \\
&= \langle p_{168} p_{137}, \dots \rangle,
\end{aligned}
\tag{4.30}
$$

which has dimension 52.

Next, by computing the images of the 52 basis elements under the raising operators X_i, $i=1,2,3$, one finds the highest weight vectors in $S^2(S_{1^3}\left((\mathbf{2},\mathbf{2},\mathbf{2})\right))$ (4.30), which result to span a 5-dimensional sub-space of such a weight space. As they are rather complicated (and not particularly illuminating) homogeneous polynomials of degree 2 in the *Plücker coordinates* $p_{ijk}(t)$, we will refrain from reporting them here explicitly.

Then, by recalling (4.21), one can express p_{ijk} in terms of the coordinates c_{ij}, thus obtaining a 3-dimensional sub-space. Let $\{g_1, g_2, g_3\}$ be a basis of this sub-space; therefore, $(\mathbf{1},\mathbf{1},\mathbf{3})^{\oplus 3} \subset S_{2^3}\left((\mathbf{2},\mathbf{2},\mathbf{2})\right)$ (*cfr.* (4.18)) is spanned by $\left\{g_i, Y_3(g_i), Y_3^2(g_i)\right\}_{i=1,2,3}$. The $SL\left(2,\mathbb{R}\right)^3$-representation $V(0,0,2) =: (\mathbf{1},\mathbf{1},\mathbf{3})$ has a unique invariant in $S^2 V(0,0,2) =: (\mathbf{1},\mathbf{1},\mathbf{3})_s^{\otimes 2}$, given by the Cartan-Killing metric in the adjoint (spin $s=1$) irrep. $\mathbf{3}$ of the third copy of $SL\left(2,\mathbb{R}\right)$ in $SL\left(2,\mathbb{R}\right)^3$ itself, and whose expression in terms of $\left\{g, Y_3(g), Y_3^2(g)\right\}$ is given by

$$
2g Y_3^2(g) - (Y_3(g))^2 .
\tag{4.31}
$$

Thus, in $S^2\left(S_{2^3}\left((\mathbf{2},\mathbf{2},\mathbf{2})\right)\right) \subset S_{4^3}\left((\mathbf{2},\mathbf{2},\mathbf{2})\right)$, one gets 3 $\left(SL_h\left(3,\mathbb{R}\right) \times SL\left(2,\mathbb{R}\right)^3\right)$-invariant homogeneous polynomials of degree 12 in the $(\mathbf{3},\mathbf{2},\mathbf{2},\mathbf{2})$, which can be checked to be linearly independent as polynomials in the c_{ij}'s.

By considering also the results of the same procedure repeated for $(\mathbf{3},\mathbf{1},\mathbf{1})^{\oplus 3} \subset S_{2^3}\left((\mathbf{2},\mathbf{2},\mathbf{2})\right)$ as well as for $(\mathbf{1},\mathbf{3},\mathbf{1})^{\oplus 3} \subset S_{2^3}\left((\mathbf{2},\mathbf{2},\mathbf{2})\right)$ (*cfr.* (4.18)), one obtains a total of 3 $SL\left(2,\mathbb{R}\right)^3$-invariant homogeneous polynomials of degree 12 in $S^2\left(S_{2^3}\left((\mathbf{2},\mathbf{2},\mathbf{2})\right)\right) \subset S_{4^3}\left((\mathbf{2},\mathbf{2},\mathbf{2})\right)$.

4.3.4 *stu* **Triality**

In order to determine the remaining relevant 6 invariants of degree 12, one can now use the action of the symmetric group S_3 on $R = (\mathbf{2},\mathbf{2},\mathbf{2})$ by permuting the tensor components, so $(12) \in S_3$ will map x_{abc} to x_{bac}, *etc.*. Consequently, S_3 will also act on the c_{ij}'s, as well as on the Plücker coordinates p_{ijk}. As we will see below, in the context of *stu* black holes, the invariance under S_3 must be enforced, because it corresponds to the *triality symmetry* [33] exhibited by such a model of $\mathcal{N}=2$, $D=4$ supergravity.

Using this action, the 3 invariants just found in Sec. 4.3.3 give rise to the required set of 9 invariants.

Including the invariant from Sec. 4.1 (which, as mentioned above, matches the one obtained in Sec. 4.3.2), one gets a total of 10 invariants of degree 12 in the c_{ij}'s.

Thus, we constructed a basis $\{\mathbf{I}_{12,\alpha}\}_{\alpha=1,\dots,10}$ for the 10-dimensional vector space of $\left(SL_h\left(3,\mathbb{R}\right) \times SL\left(2,\mathbb{R}\right)^3\right)$-invariant homogeneous polynomials of degree 12 in the $(\mathbf{3},\mathbf{2},\mathbf{2},\mathbf{2})$ (resulting from Table (2.45)).

As degree-12 homogeneous polynomials in the $c_{ij} \in (\mathbf{3},\mathbf{2},\mathbf{2},\mathbf{2})$ of $SL_h\left(3,\mathbb{R}\right) \times SL\left(2,\mathbb{R}\right)^3$ (realized *e.g.* through the identification (4.22)), they have far too many terms, rendering their explicit expression

cumbersome and not particularly illuminating. However, we observe that each of the invariants $\mathbf{I}_{12,\alpha}$ can be rewritten as

$$\mathbf{I}_{12,\alpha} = \sum_{\beta=1}^{10} C_{\alpha\beta} M_\beta + ..., \tag{4.32}$$

where $C_{\alpha\beta} \in \mathbb{Z}$, and M_β ($\beta = 1, \ldots, 10$) denotes the following set of monomials:

$$
\begin{aligned}
M_1 &: \ = c_{18}^4 c_{23}^2 c_{25} c_{26} c_{31}^3 c_{32}, \quad M_2 := c_{18}^4 c_{23}^2 c_{25}^2 c_{31}^2 c_{32}^2, \quad M_3 := c_{18}^4 c_{22} c_{24} c_{25}^2 c_{31}^3 c_{33}, \\
M_4 &: \ = c_{18}^4 c_{22} c_{23} c_{26} c_{27} c_{31}^4, \quad M_5 := c_{18}^4 c_{22} c_{23} c_{25} c_{27} c_{31}^3 c_{32}, \quad M_6 := c_{18}^4 c_{22}^2 c_{27}^2 c_{31}^4, \\
M_7 &: \ = c_{11}^3 c_{16} c_{22}^2 c_{27}^2 c_{33} c_{38}^3, \quad M_8 := c_{11}^3 c_{14} c_{22}^2 c_{27}^2 c_{35} c_{38}^3, \quad M_9 := c_{11}^3 c_{14} c_{22} c_{23} c_{26} c_{27} c_{35} c_{38}^3, \\
M_{10} &: \ = c_{11}^3 c_{14} c_{23}^2 c_{26}^2 c_{35} c_{38}^3,
\end{aligned}
\tag{4.33}
$$

which completely characterize each $\mathbf{I}_{12,\alpha}$. Indeed, the dots in the right-hand side of (4.32) stand for many other linear combinations of monomials which are linearly independent on the M_β's, but which can be determined by the action of the whole group $SL_h(3,\mathbb{R}) \times SL(2,\mathbb{R})^3$ itself, once the $C_{\alpha\beta}$'s are specified. Of course, there are many sets of 10 monomials with the property (4.32). Given the set M_β (4.33), each element $\mathbf{I}_{12,\alpha}$ of the 10-dimensional complete basis $\{\mathbf{I}_{12,\alpha}\}_{\alpha=1,\ldots,10}$ constructed above can be written as a vector in $\mathbb{Z}^{10}$.

Let us make some examples.

The invariant F_0 (4.11), constructed in Sec. 4.1 as well as in Sec. 4.3.2, has coordinates[31]

$$F_0 \equiv (0, 0, 0, -2, 4, 1, 4, 4, -8, 4, 4). \tag{4.34}$$

On the other hand, the following three vectors correspond to the aforementioned basis $\{g_1, g_2, g_3\}$ the 3-dimensional sub-space of invariants obtained from $(\mathbf{1}, \mathbf{1}, \mathbf{3})^{\oplus 3} \subset S_{2^3}((\mathbf{2}, \mathbf{2}, \mathbf{2}))$ (*cfr.* Sec. 4.3.3):

$$
\begin{aligned}
g_1 &\equiv (-6, 6, 1, 0, 0, 0, 0, 0, 9, -9, -9); \\
g_2 &\equiv (2, -2, -1, 2, -4, -2, 10, 10, -15, 5, 5); \\
g_3 &\equiv (2, -1, 0, 2, -2, -1, 6, 4, -8, 4, 4).
\end{aligned}
\tag{4.35}
$$

As mentioned above, the *stu triality* symmetry (implemented as the symmetric group S_3) permutes the subspaces $(\mathbf{1}, \mathbf{1}, \mathbf{3})^{\oplus 3}$, $(\mathbf{1}, \mathbf{3}, \mathbf{1})^{\oplus 3}$ and $(\mathbf{3}, \mathbf{1}, \mathbf{1})^{\oplus 3}$; as a consequence, there is a 3-dimensional sub-space of *triality-invariant* $\left(SL_h(3,\mathbb{R}) \times SL(2,\mathbb{R})^3\right)$-invariants in their direct sum,[32] which is the space spanned by the vectors

$$
\begin{aligned}
F_1 &\equiv (1, -1, 1, 1, -2, -1, 3, 3, -14, 3, 3); \\
F_2 &\equiv (-5, 5, -5, 7, -14, -1, -7, -7, -10, -7, -7); \\
F_3 &\equiv (4, -3, 0, 4, -6, -3, 4, 2, -22, 8, 8).
\end{aligned}
\tag{4.36}
$$

By adding the invariant F_0 (4.11) (or equivalently, through (4.32)-(4.33), (4.34)), which is also *triality-invariant*, out of $\{\mathbf{I}_{12,\alpha}\}_{\alpha=1,\ldots,10}$ one gets a 4-dimensional basis $\{F_0, F_1, F_2, F_3\}$ for degree-12 homogeneous polynomials invariant under the action of $S_3 \times SL_h(3,\mathbb{R}) \times SL(2,\mathbb{R})^3$ on $(\mathbf{3}, \mathbf{2}, \mathbf{2}, \mathbf{2})$. Thus, as anticipated in Sec. 4, 4 is the (real) dimension of the vector space of degree-12 $\left(SL_h(3,\mathbb{R}) \times SL(2,\mathbb{R})^3\right)$-invariant polynomials relevant for the 3-centered BHs in the $\mathcal{N} = 2$, $D = 4$ *stu* model.

---

[31] What we actually write in (4.34), (4.35) and (4.36) are 11 integers $(a_1, ..., a_{11})$ such that

$$\sum_{\alpha=1}^{10} a_\alpha \mathbf{I}_{12,\alpha} + a_{11} F_0 = 0.$$

[32] Its complement is the direct sum of three 2-dimensional (irreducible) S_3-representations.

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